

# Future lander observation by Japanese Mars EDL mission

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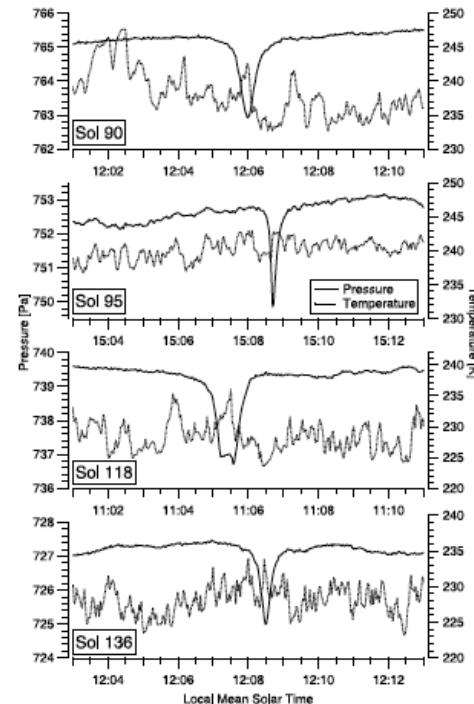
H. Senshu(PERC / Chiba Inst. of Tech.)

# Meteorological Interest on Martian Surface

- Source of Physical components
  - (Dust, Water Vapor,..)
- Boundary Layer
  - ( Source / Sink of Momentum)
  - Transport Physical Components
- Others
  - in-situ (e.g. Heat Inertia, Roughness, ... )

# Meteorological Observation:

1. Environmental Monitor and meteorological observation (10 minutes mean)
  1. Temperature
  2. Wind Velocity, Wind Direction
  3. Pressure
  4. Short / Long wave radiation
  5. Thermal Inertia of soil  
(1 hour mean of surface temperature)
2. Dust devil Structure
  1. Pressure drop (2Pa) of Dust devil
  2. Wind velocity / direction
  3. Numbers or Amount of dust  
( require Dust particle counter or LIDAR)
  4. Opacity (Navigation Camera)
3. Power spectrum of wind (Extra)
  1. Wind velocity / Pressure at 2s period (up to 60sol)



Observed Pressure while  
Dust devil Event

# Instruments

- BASIC Components
  - Thermometer
  - Barometer
  - Anemometer
  - (CAMERA)
- Dust Measurements
  - Particle Counter
  - LIDAR

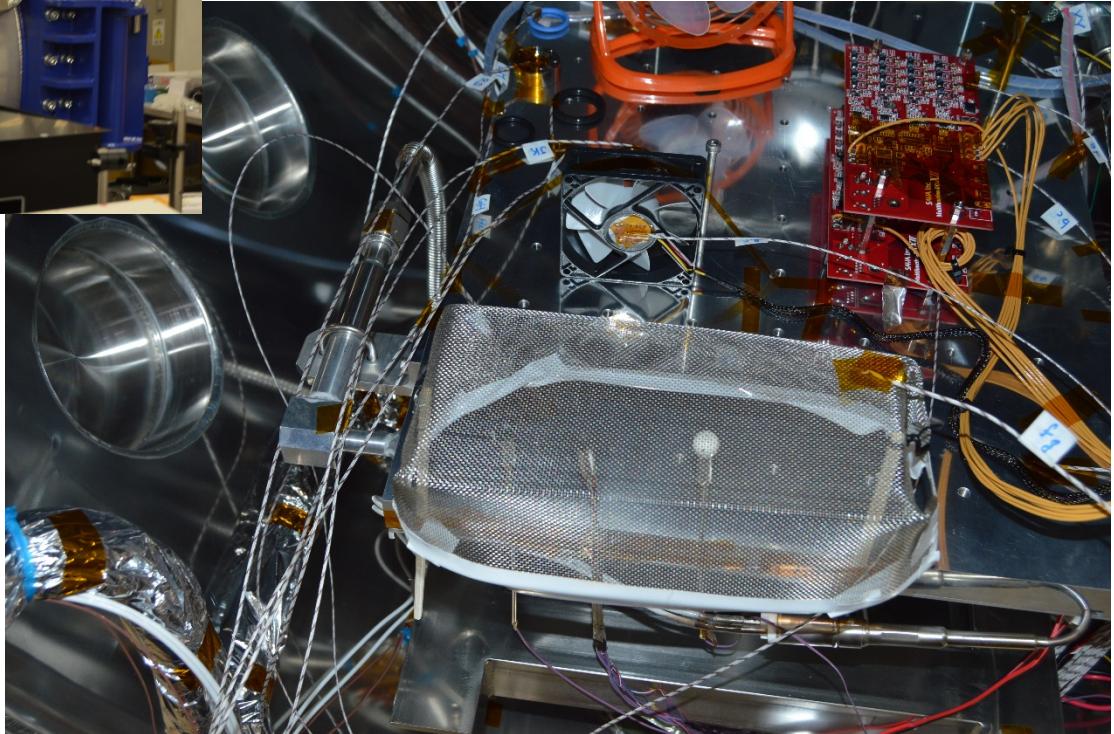
Talk about :  
developing / testing status some instruments

# TESTING ENVIRONMENT



Mars Environmental Simulation Chamber  
/ PERC

5-10hPa (1000 – 0 hPa)  
0 : -120°C (40 : -120°C)  
CO<sub>2</sub> or Ar (Lower -80°C)



# Globe Thermo-Radiative-Anemometer



using on Earth with Bio-sensors  
for human health meteorology  
(Heatstroke)

(Nakayoshi /Tokyo Univ. of Sci. )

- 2 globes of different colors + 1 more black globe ( $\phi 12$ )
- different absorption rates of radiation  
(Shortwave (Solar radiation ) and Longwave(mainly Ground Radiation)).
- measurement of each temperature of globes (by thermocouple).
- 1 more black globe is heated.

Tested in Mars Environment Chamber

# Globe Sensors Temperature determination factor

$$C \downarrow gbh / A (dT \downarrow gbh / dt) = (1 - \alpha \downarrow b) S + \varepsilon \downarrow b L - \varepsilon \downarrow b \sigma T \downarrow gbh^{\uparrow 4} - h(T \downarrow gbh - T \downarrow a) + H \downarrow input$$

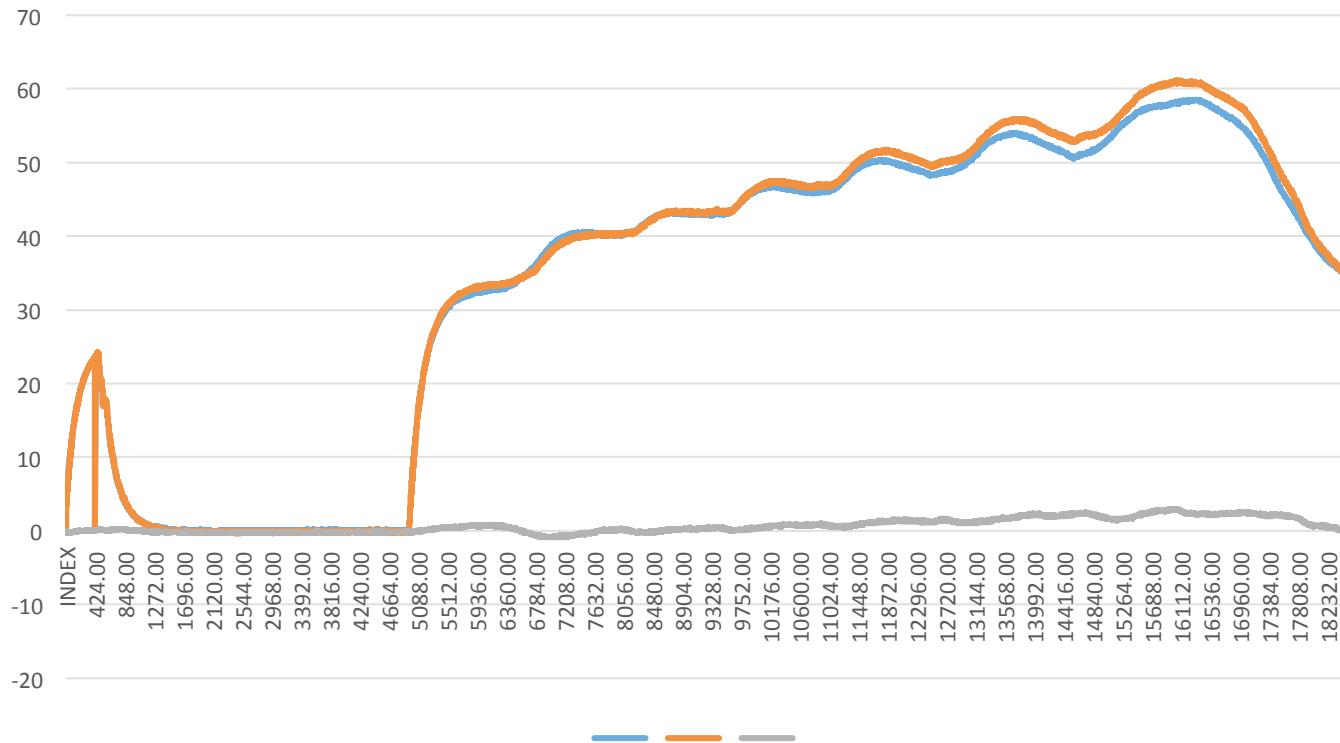
$$C / A (dT \downarrow gb / dt) = (1 - \alpha \downarrow b) S + \varepsilon \downarrow b L - \varepsilon \downarrow b \sigma T \downarrow gb^{\uparrow 4} - h(T \downarrow gb - T \downarrow a)$$

$$C / A (dT \downarrow gw / dt) = (1 - \alpha \downarrow w) S + \varepsilon \downarrow w L - \varepsilon \downarrow w \sigma T \downarrow gw^{\uparrow 4} - h(T \downarrow gw - T \downarrow a)$$

C: Thermal Capacity A:Surface Area S,L:Short,Long wave radiative flux

$\alpha$ :Albedo  $\varepsilon$ :emissivity  $\sigma$ :Stefan-Boltzmann constant  $H_{input}$ :Heater's Heat input

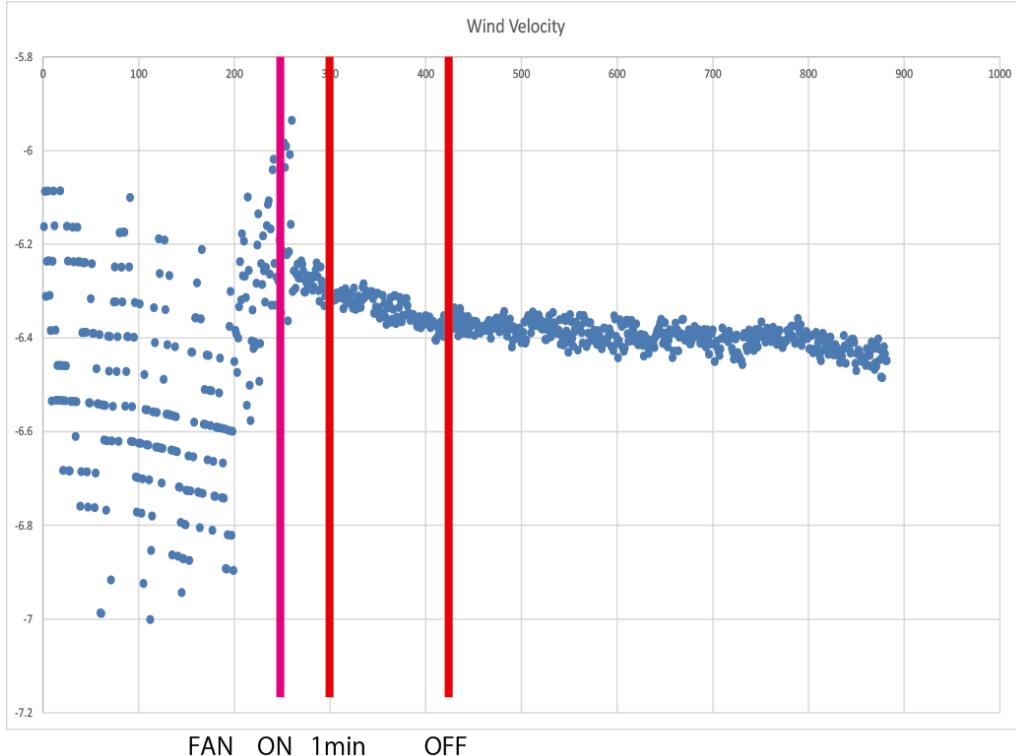
# Radiation



difference between globes:

gray line : feel Long wave (due to difference of emissivity)

# Anemometer



Calculated Wind velocity  
(1 min Running mean)

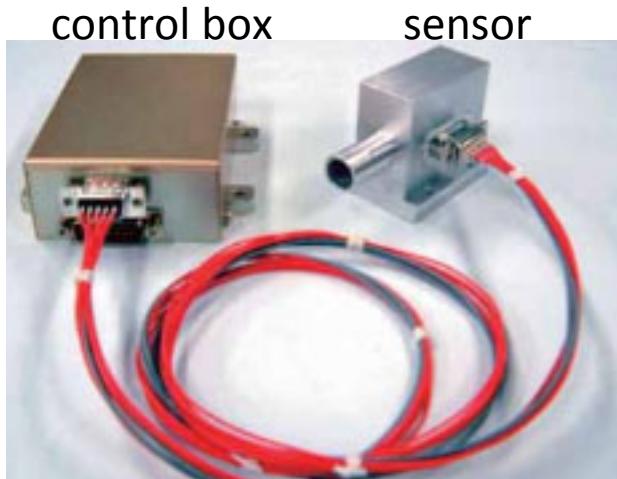
Left side of vertical FAN ON line :  
very turbulent air condition.  
(because of injection CO<sub>2</sub>)

NOTE: using Heat Capacity value at 1000hPa Air  
So Calculated value is not meaningless.

# Accuracy

- On Earth
  - Wind Velocity(0.24 m/s)
  - Short Wave flux ( $19.1\text{W/m}^2$ )
  - Long Wave flux ( $14.8\text{W/m}^2$ )
- On Mars
  - Wind Velocity -> detectable?
  - Short Wave (maybe same: twice larger relatively)
  - Long Wave (maybe same: 10times larger relatively)

# Barometer



Crystal Oscillator:

- Impedance is a Function of Friction (and temperature)
- Dependency can control with cutting angle  
(this sensor mainly Impedance - friction(pressure)  
Frequency - Temperature )
- total 200g , 10cm x 10cm x 5cm

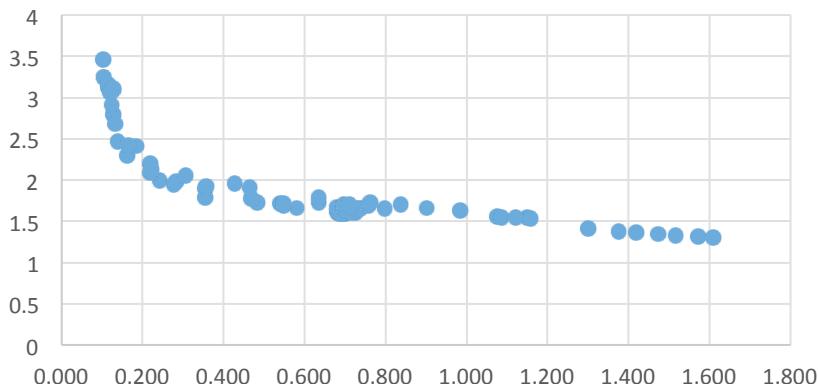
Kurihara(Hokkaido Univ.)

Using on Rocket observation troposphere to mesosphere:

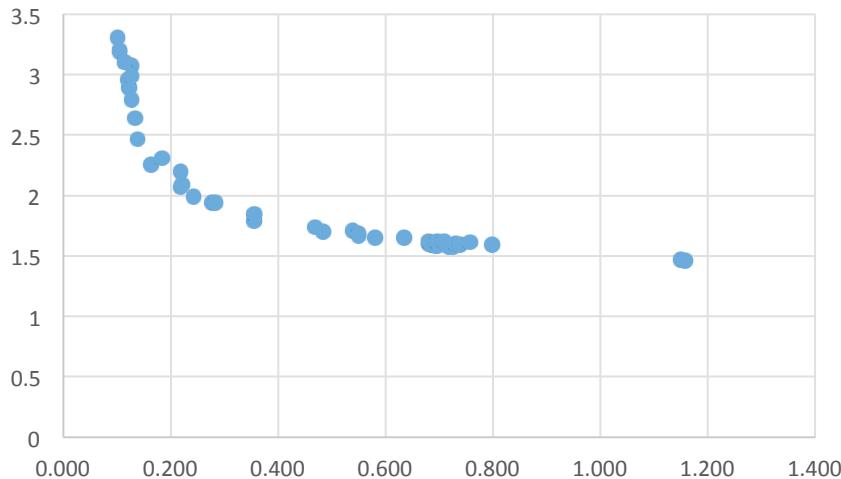
- wide dynamic range
- robust for vibration at launch time

# Pressure

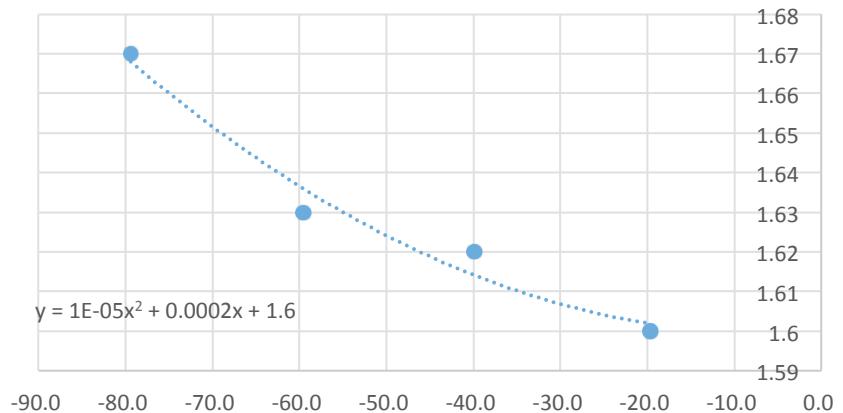
Barometer(y : Barometer x : ControlPanel/  
pressure gauge)



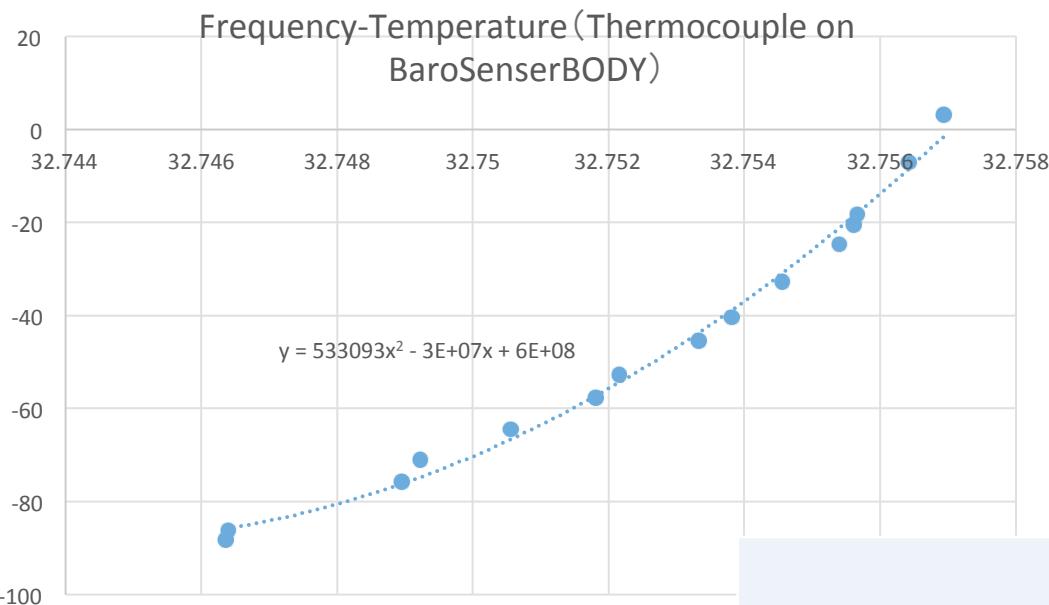
Corrected with Temperature



Dependency on Temperature(6.8hPa)



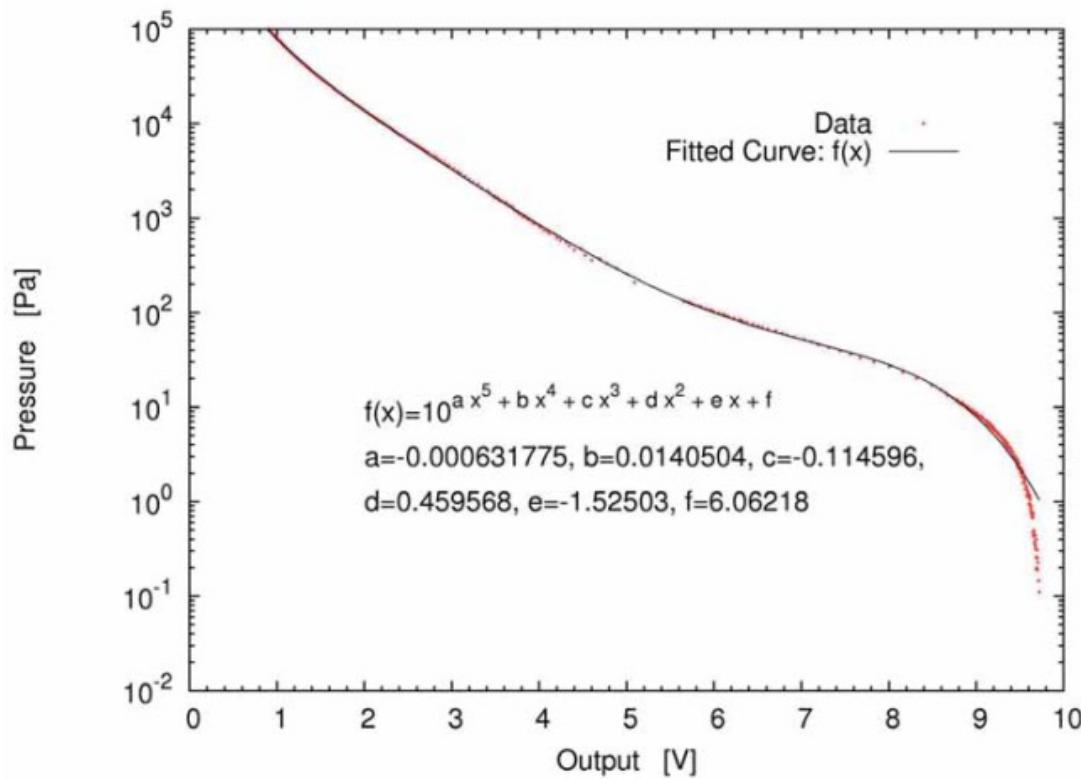
# Thermocouple vs Temperature from frequency



	Outside Thermocouple	Inner Thermocouple	Temperature Frequency
22:56:30	-71.94	-94.4	-83.2389
23:00:32	-54.13	-74.7	-68.7101
23:02:20	-46.35	-58.7	-60.2459
23:03:32	-39.58	-53.8	-54.0083
23:04:26	-37.44	-46.3	-49.5689
23:06:06	-29.47	-36.1	-41.0071
23:09:26	-12.48	-17.0	-24.3147

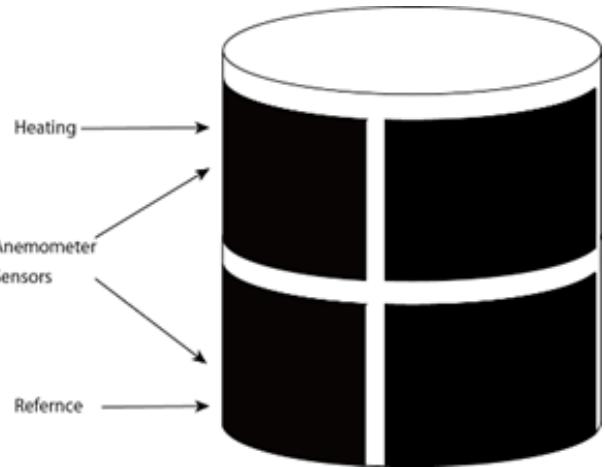
# Accuracy of Barometer

- 0.1Pa on Martian Surface (Tunable)



Calibration in air

# Anemometer



- Concept

- Split Film around cylinder
- Top film is heated
- Pt heater
- Wind direction is calculated difference of sensor pair

# Radiation Thermometer

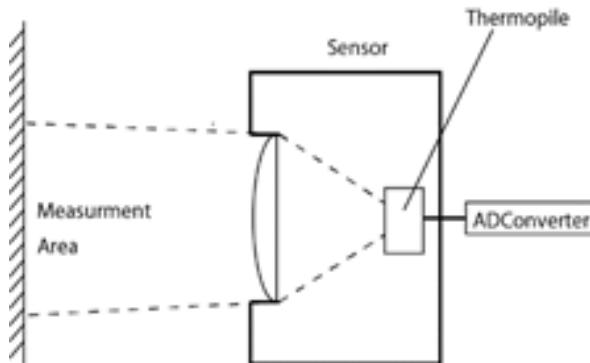


$$C/A \left( \frac{dT_{gb}}{dt} \right) = (1 - \alpha_{gb})S + \varepsilon_{gb} L - \varepsilon_{gb} \sigma T_{gb}^4 - h(T_{gb} - T_a)$$

Cut by Ge Lens

No Wind

Radiation Thermometer



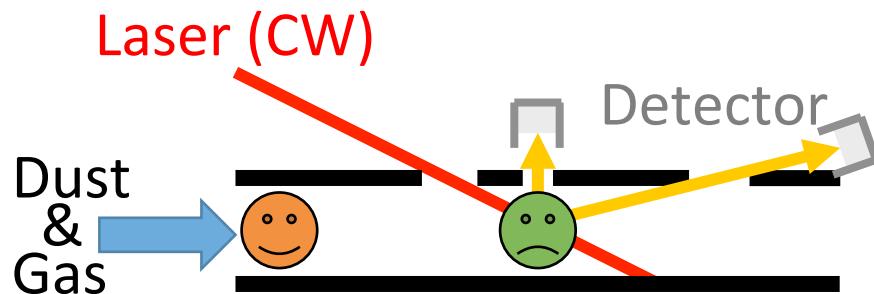
- Surface Temperature monitoring

HORIBA Ltd.

Only qualitative test:  
working but value is not validated

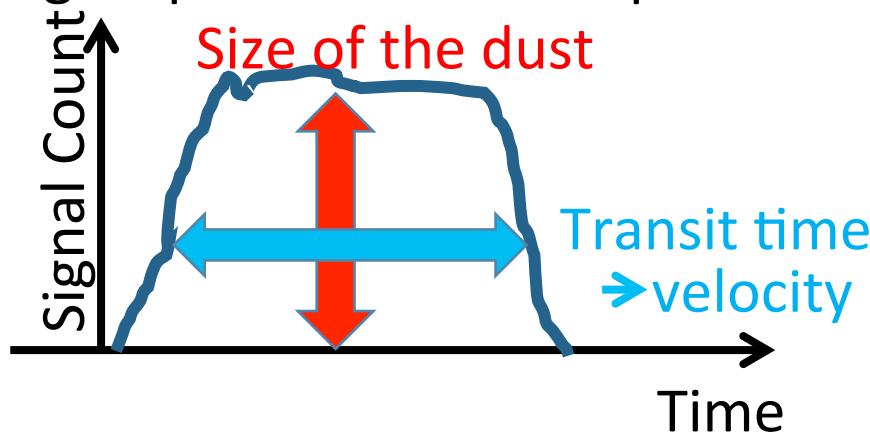
# Dust Monitoring

## Particle sensor



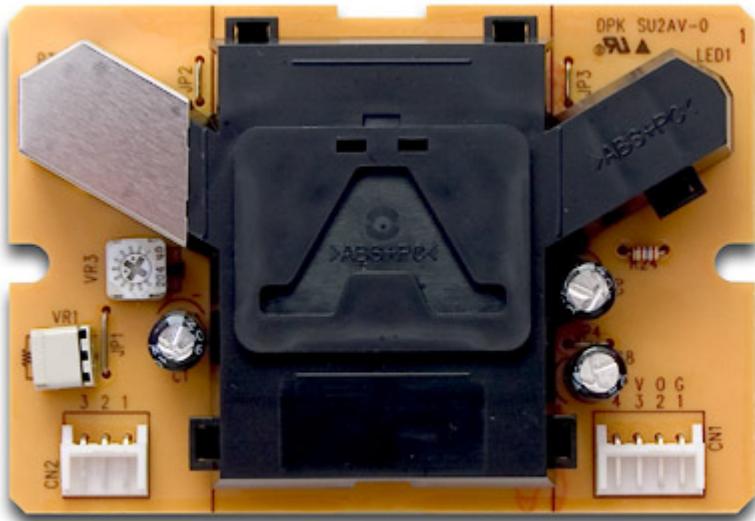
In reality, CW laser is wider ( $\sim 1\text{mm}$ ) than the size of typical dust size ( $\sim \text{a few }\mu\text{m}$ ).

Signal pattern from one particle



- Particle sensor monitors the frequency of signal from transiting dust
- Already used as particle counter in cirrus cloud
- Size distribution is divided into 5+ bins.
- Specifications:
  - Weight:
    - less than 200g (sensor part +electric part +cables)
  - Size:
    - 100mmX80mmX30mm (sensor part)
  - Power consumption
    - <1W (in run)

# Particle Counter



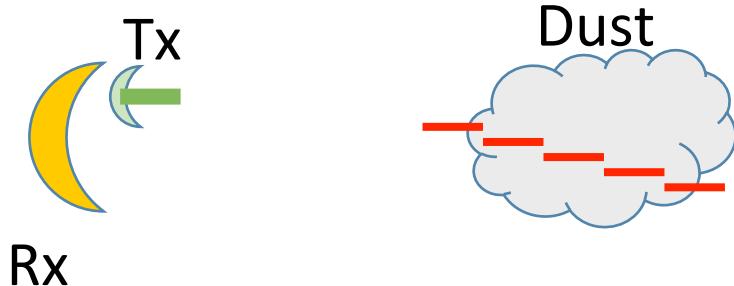
- Based Cirrus Cloud Particle Counter
- (5-6/2015 Compare with OPC)

(Fujiwara / Hokkaido Univ.)

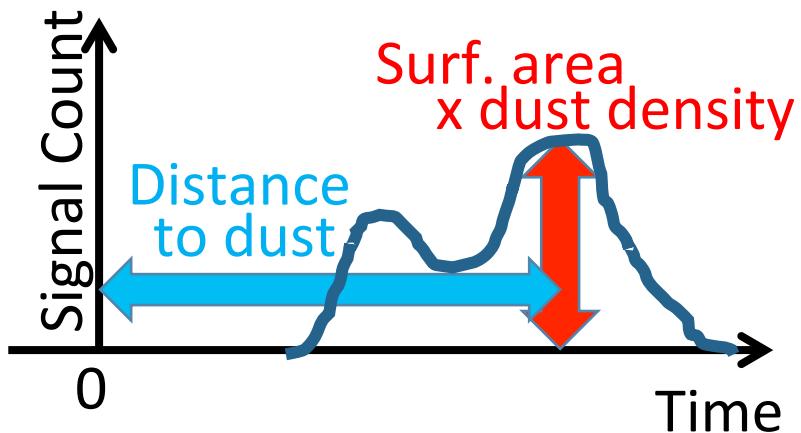
Visual Field 10mm<sup>3</sup> (=0.01cc)  
1μm particle 0.5 – 2particle (0.01 cc)  
100μm particle is much fewer

# Dust Monitoring

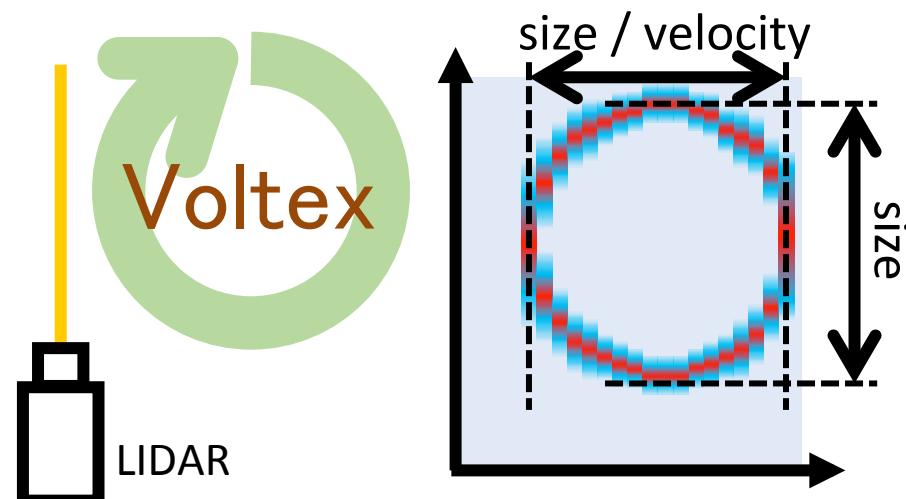
Short range LIDAR (Light Detection and Ranging)



- LIDAR transmits a pulse laser and measure the profile of returned light.



- LIDAR measures the distribution of dust grains on the line of sight.
- Comm. base instrument has been developed.
- Observe 100m dividing into 1m bins
- $\phi 100\text{mm}$ , 900g in total



# LIDAR (mirror)



2014/Apr Test each component

(Shiina / Chiba Univ.)

2015/May Assemble Sensor / Main Board -> Calibration

2015/Summer Field test

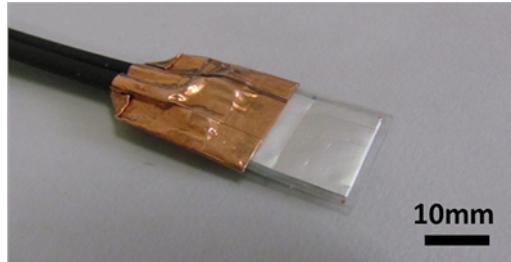
UV or Violet LED / transmitting mirror size

# Sonic Anemometer Status

- Transducer's sound Impedance very different from Martian Air's



Piezoelectric Polymer Film  
TORAY Engineering Co.



Electret Condenser Film  
(Kageyama/ Saitama Univ.)