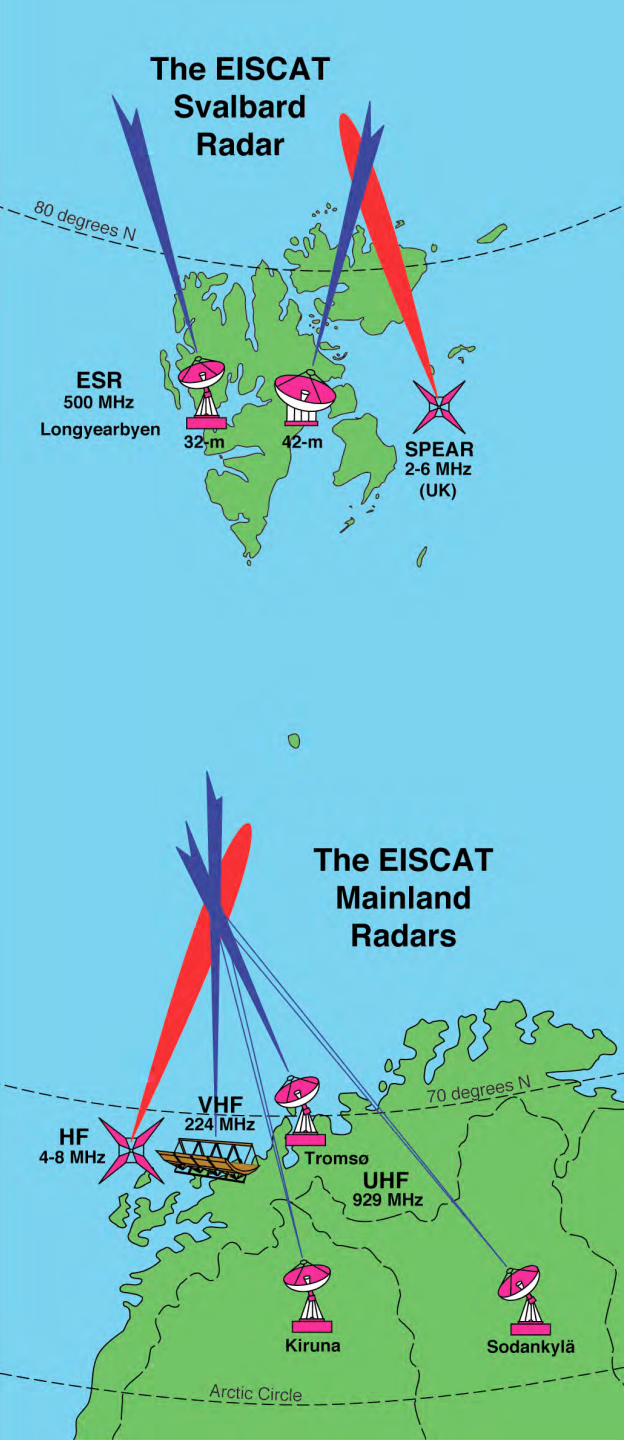


An Introduction to EISCAT_3D

Ingrid Mann

EISCAT Scientific Association, Kiruna, Sweden





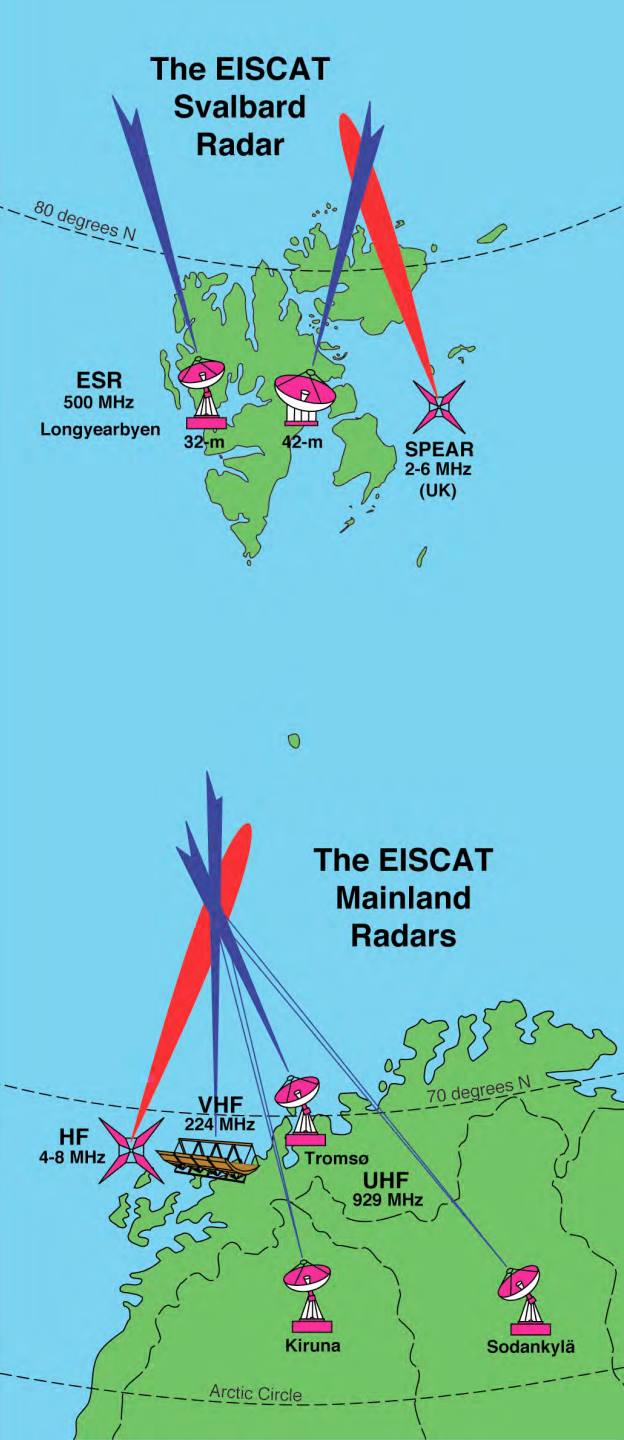
EISCAT Incoherent Scatter Radars

EISCAT scientific association

Incoherent scatter measurements

Example for other radar targets

EISCAT_3D project




EISCAT Incoherent Scatter Radars

EISCAT scientific association

Incoherent scatter measurements

Example for other radar targets

EISCAT_3D project

A large, circular radio telescope dish is mounted on a complex metal lattice structure. The dish is made of a grid of metal panels. The structure is supported by several thick legs. The background is a cloudy sky with some trees visible at the bottom.

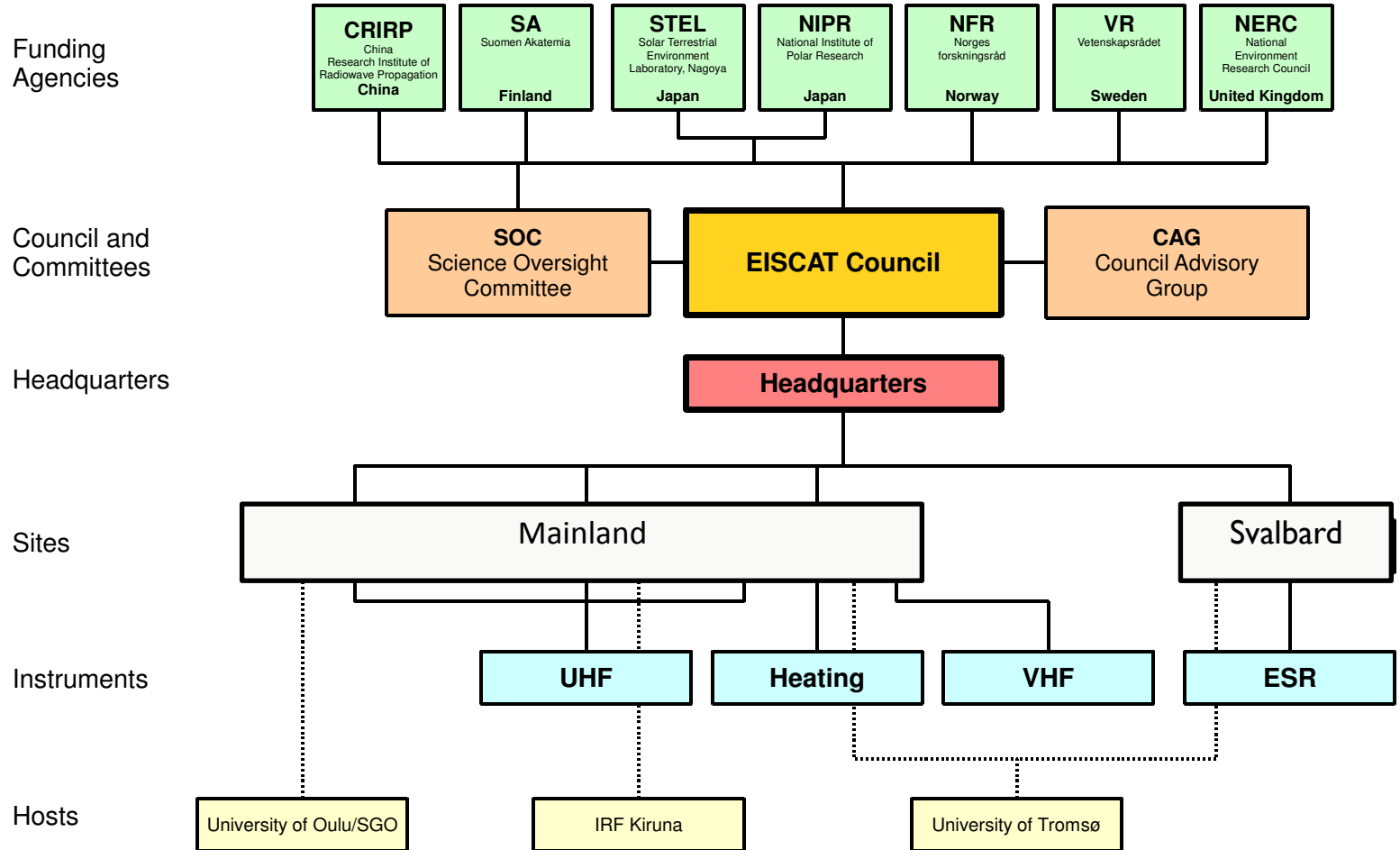
EISCAT
European Incoherent
Scatter Scientific Association

EISCAT Radars and Dynasondes



224, 500, & 928.4 MHz

EISCAT Governance



EISCAT Governance

Dr. Hiroshi Miyaoka (Council Delegate)
National Institute of Polar Research, Tokyo



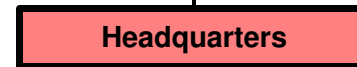
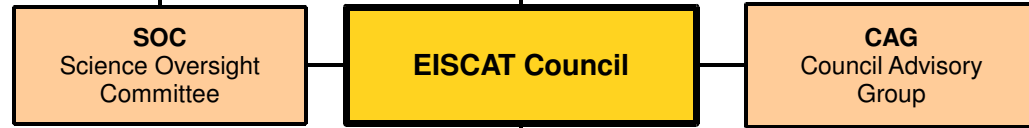
Dr. Satonori Nozawa (Council Member)
Solar Terrestrial, Environmental Lab. Nagoya University

Funding Agencies

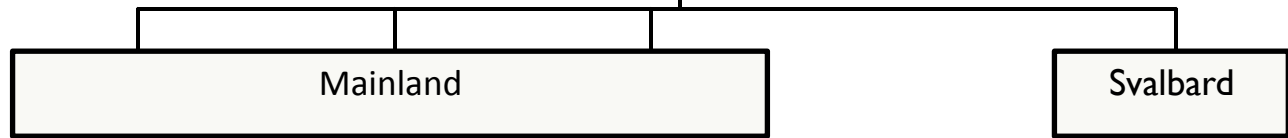


Dr. Yasunobu Ogawa (SOC Chairperson)
National Institute of Polar Research, Tokyo

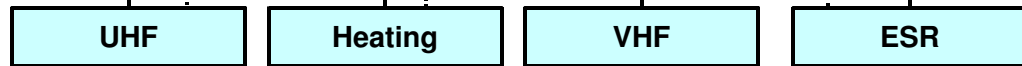
Headquarters



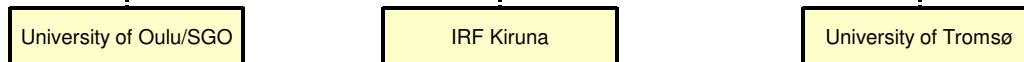
Sites



Instruments



Hosts



EISCAT

participates in global measurement campaigns

is used together with optical observations

measures in conjunction with rockets & satellites

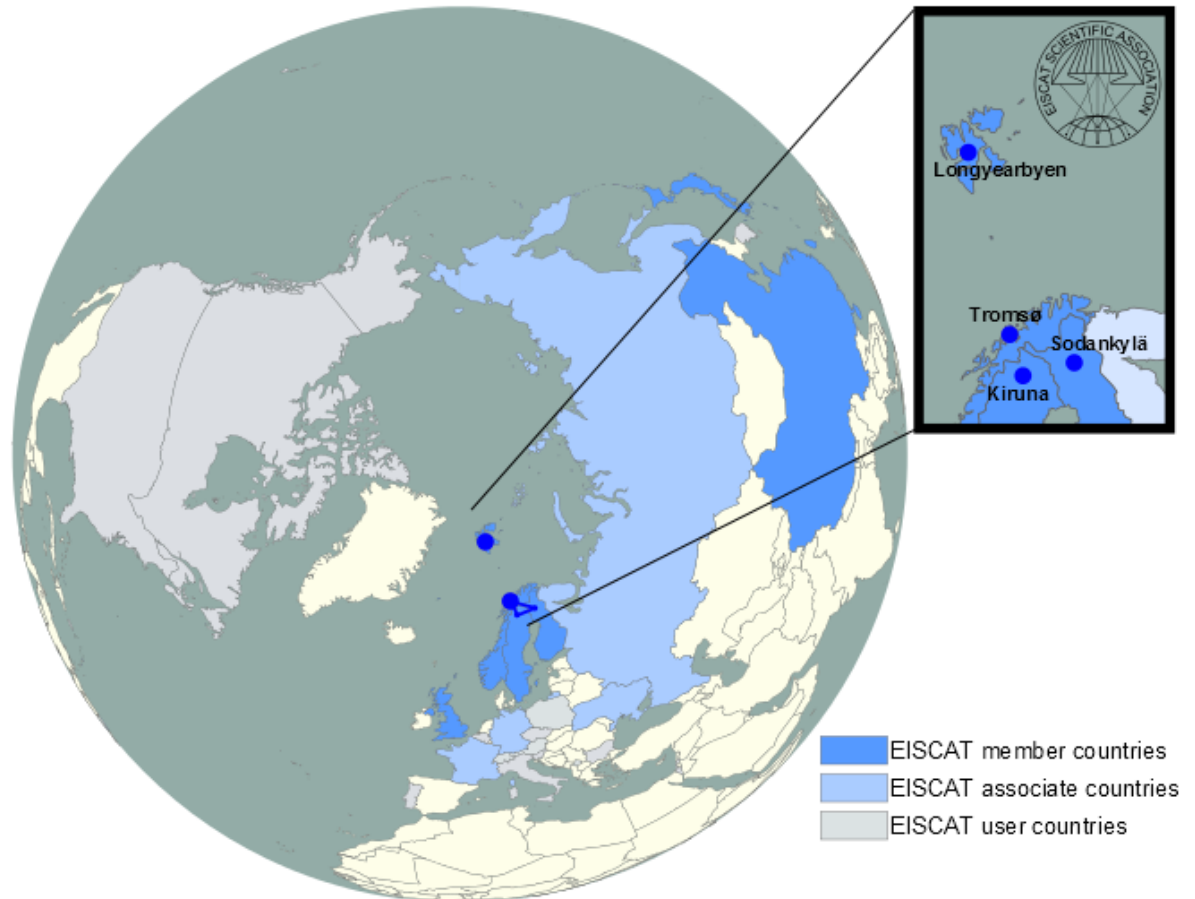
2013 Observations (est.):

1500 hrs Common

1200 hrs Special (200 Japan)

current members

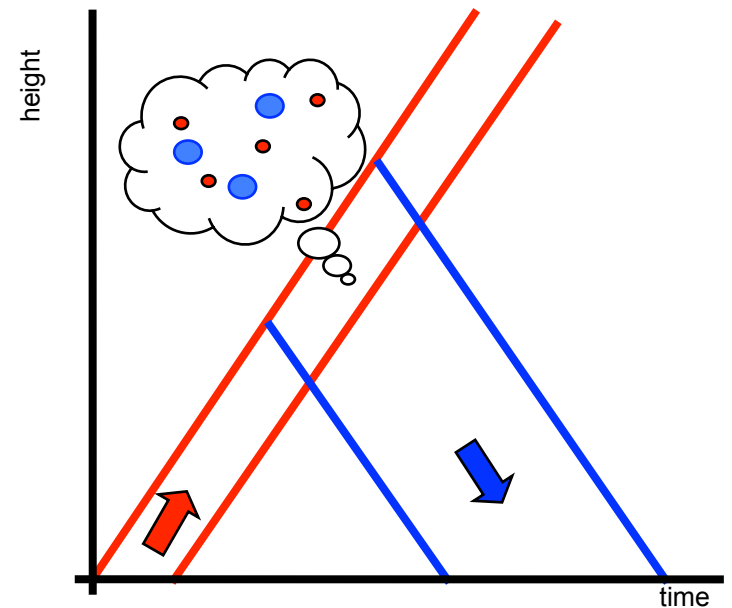
-  China
-  Finland
-  Japan
-  Norway
-  Sweden
-  United Kingdom



EISCAT Incoherent Scatter Radars

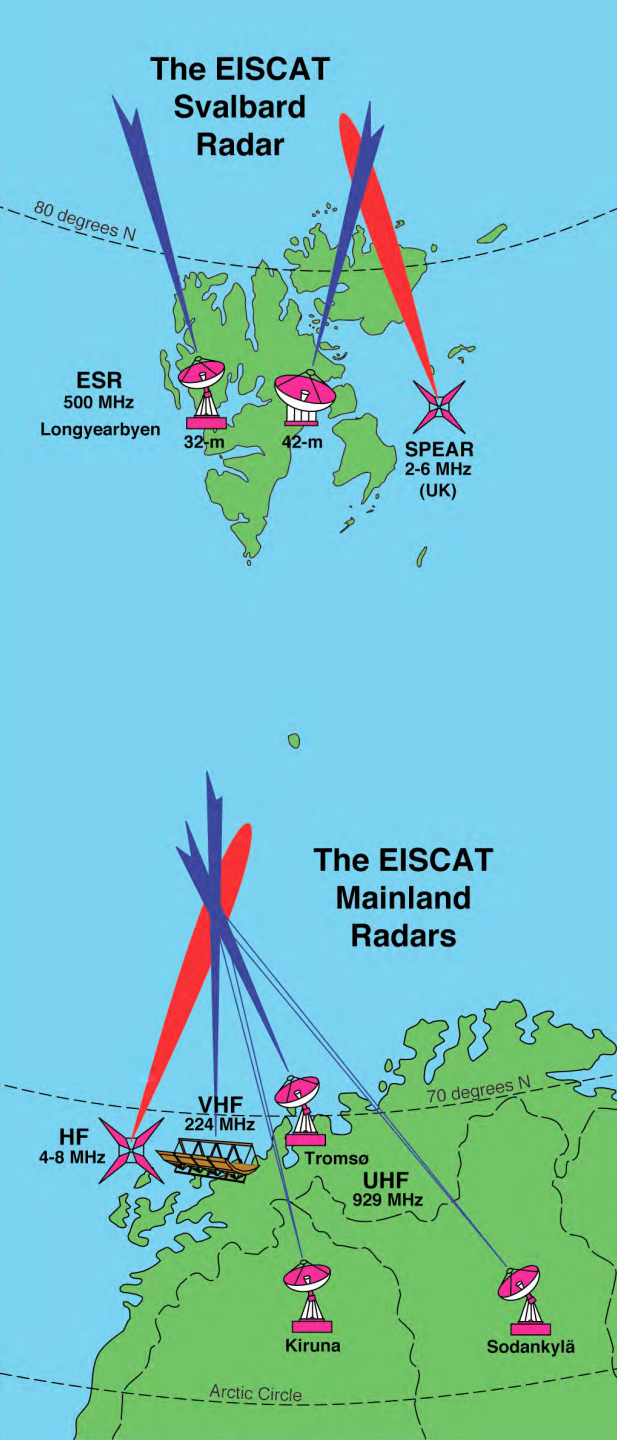
derive from data:
electron density
electron temperature
ion density
ion temperature
(.....)

Electrons scatter the radio wave:



high power
radio pulse 2 MW

sensitive receiver
signal 10^{-18} W



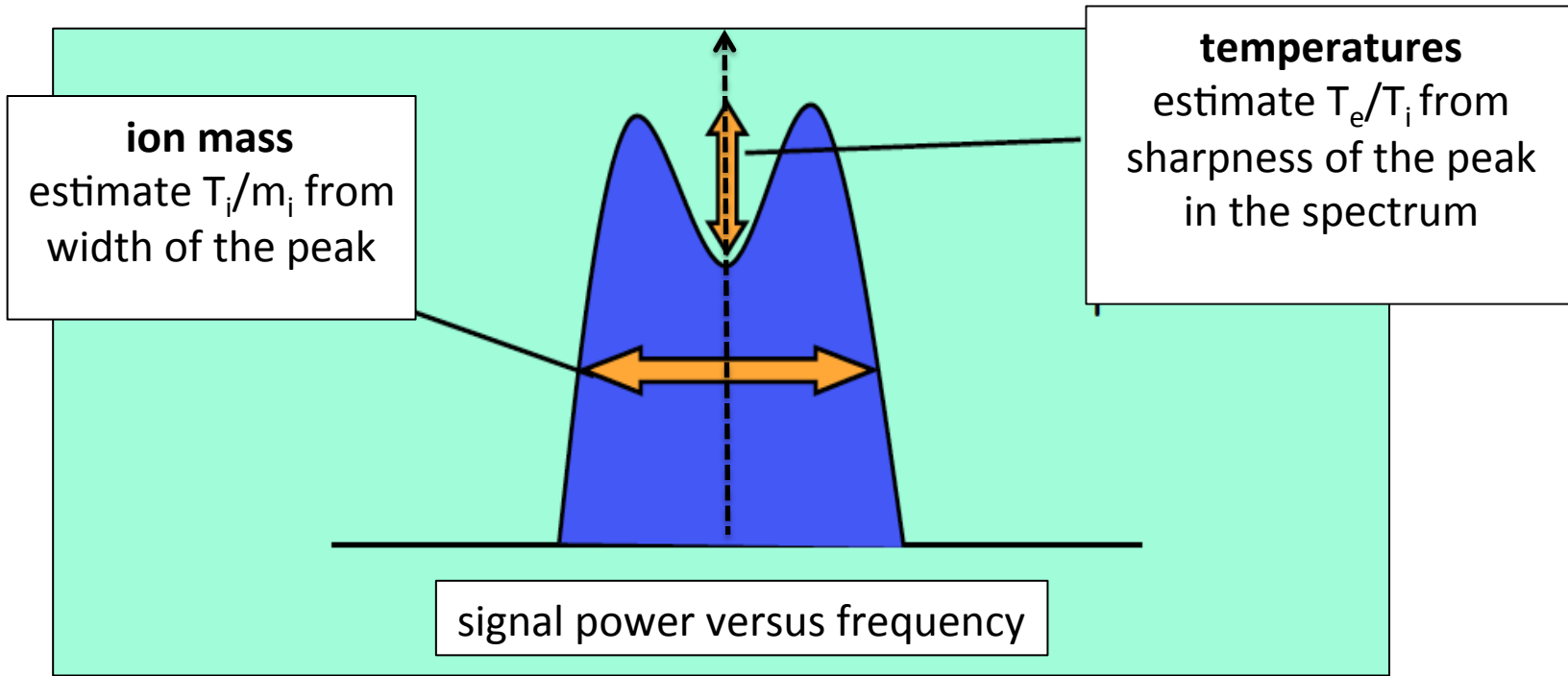
observe scattering at electrons
electron oscillations “damped”
by ions(& charged dust)

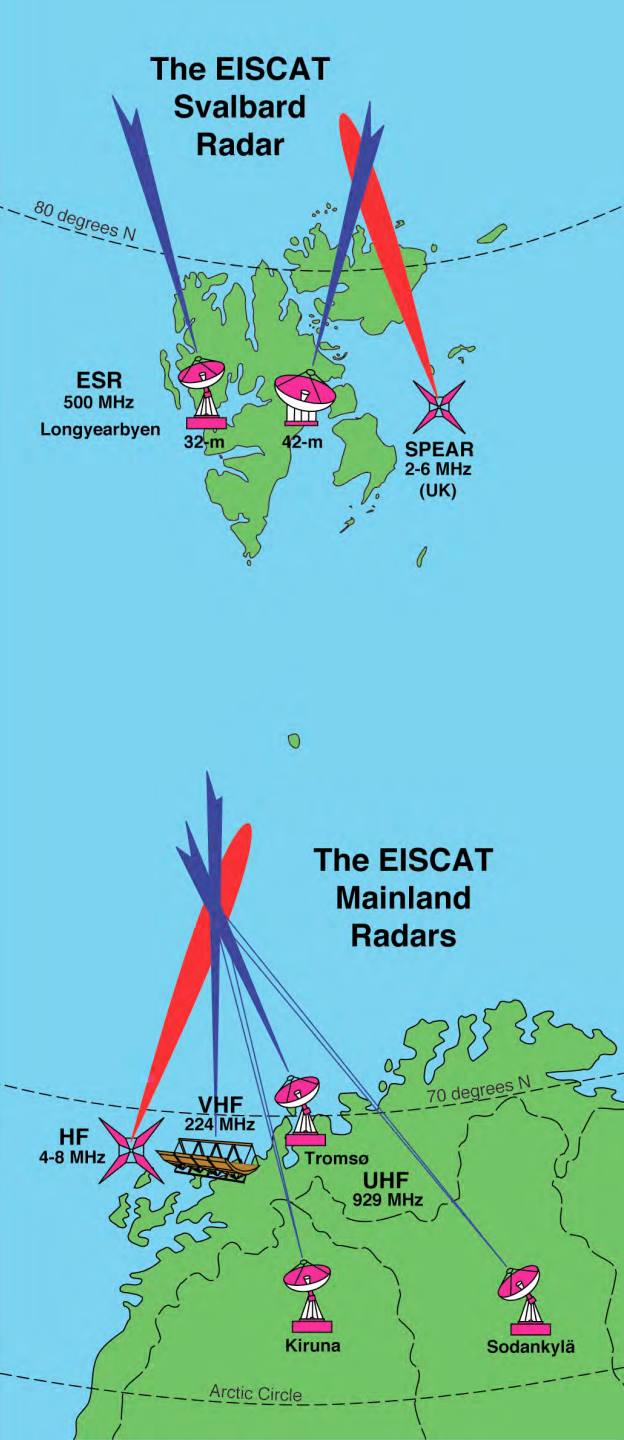
Some parameters found from scatter spectrum:

electron density (= ion) density from integrated back scattered signal

ion velocity from Doppler shift of frequency

altitude of scattered volume from time lag





EISCAT Incoherent Scatter Radars

EISCAT scientific association

Incoherent scatter measurement

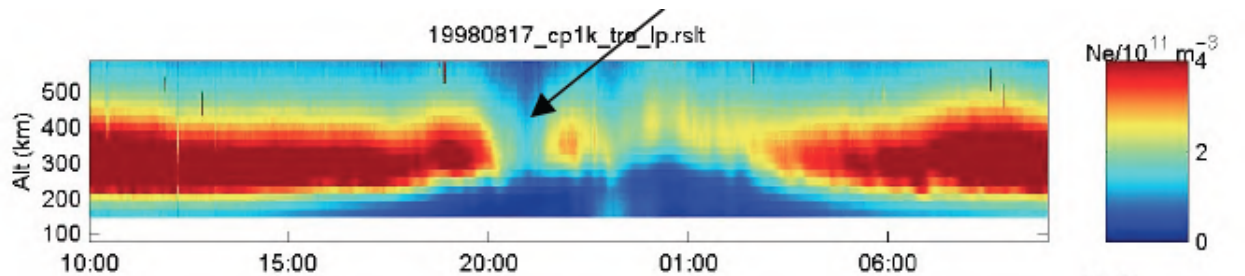
Example for other radar targets

EISCAT_3D project

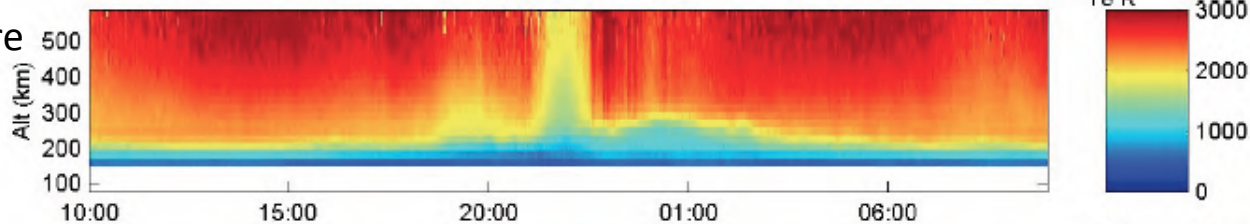
A typical summer day:

nightside minima in N_e (and T_e)

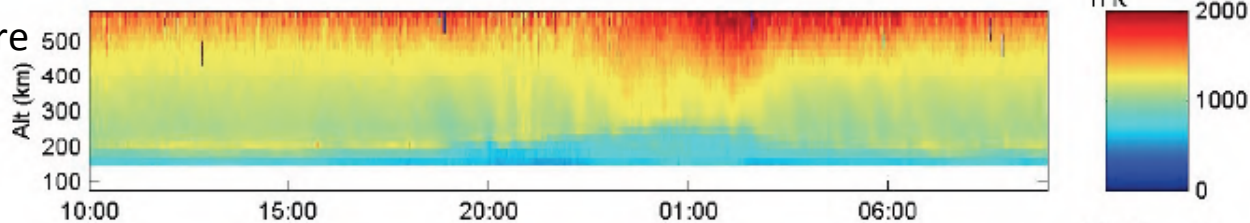
electron density



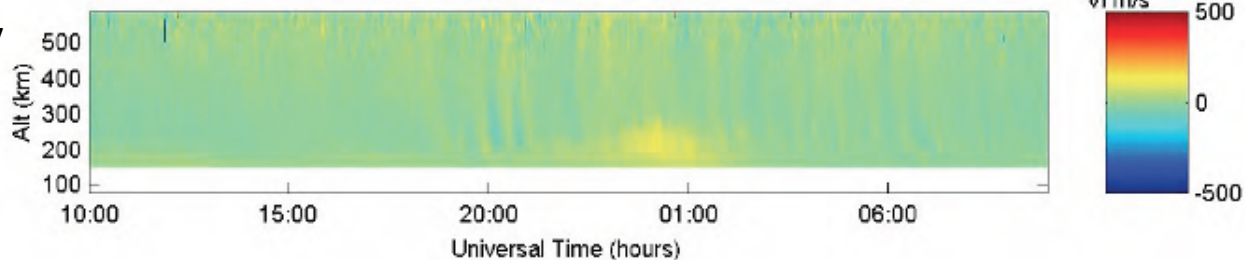
electron temperature



ion temperature



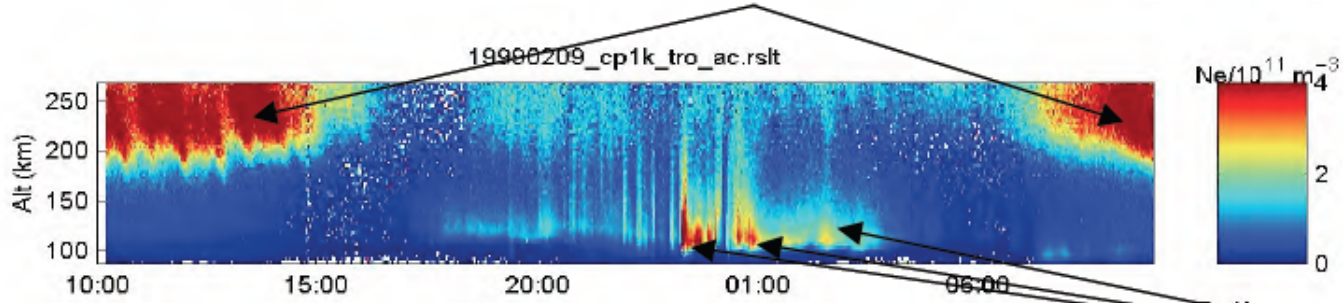
ion velocity



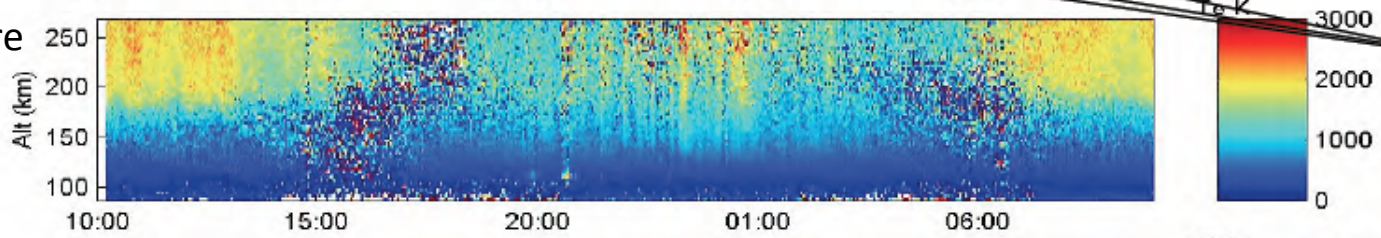
A typical winter day:

dayside maxima in N_e (and T_e)

electron density

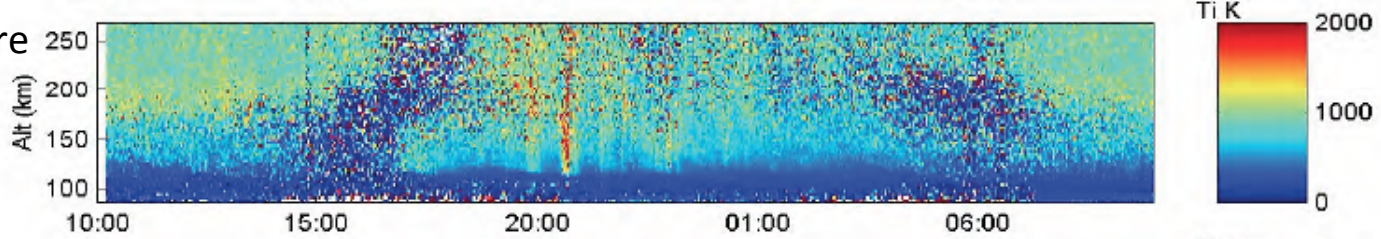


electron temperature

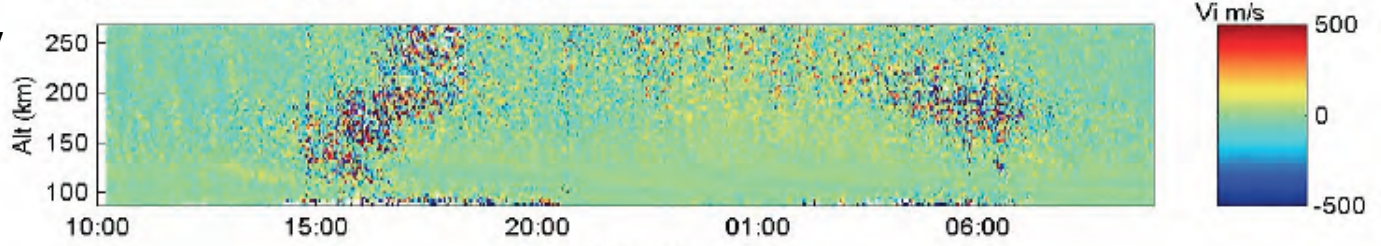


precipitation effects

ion temperature



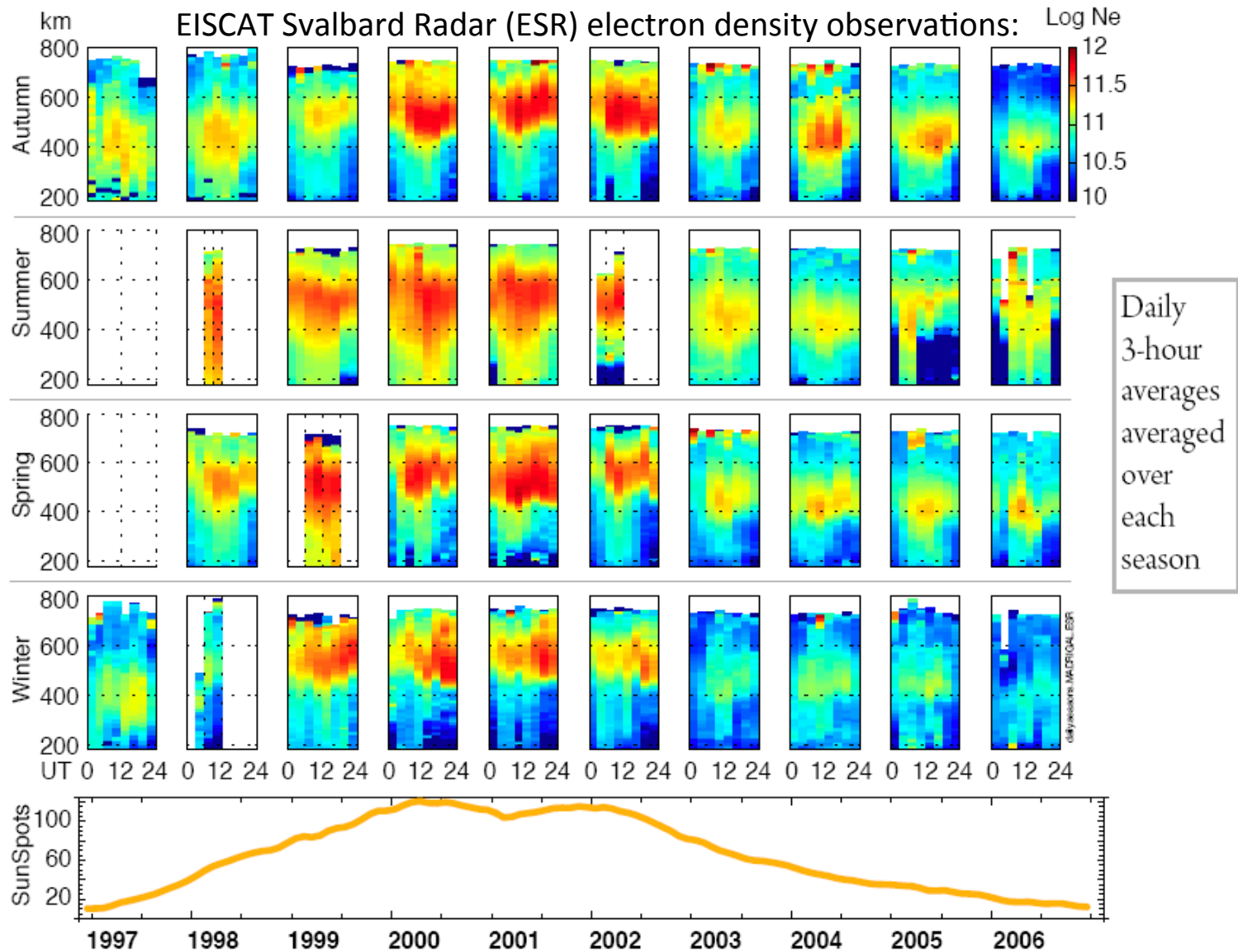
ion velocity

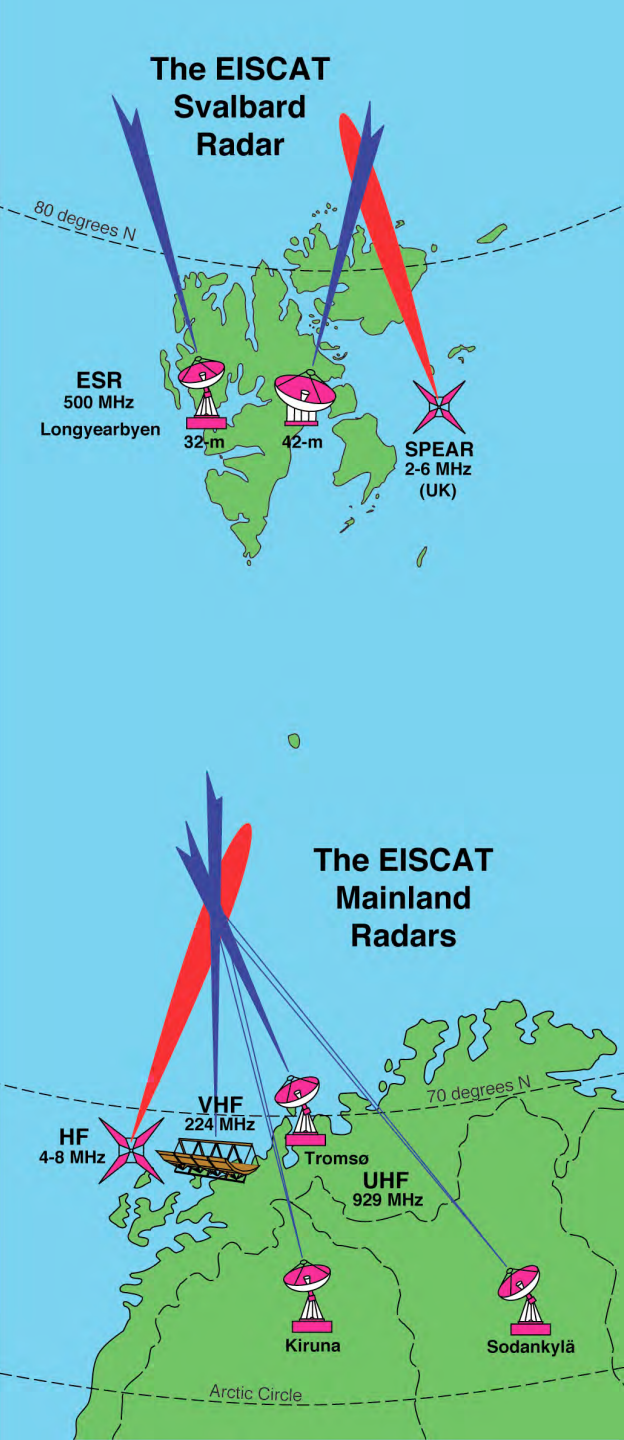


Universal Time (hours)



EISCAT Measurement During the Years





EISCAT Incoherent Scatter Radars

EISCAT scientific association

Incoherent scatter measurements

Examples for other radar targets

EISCAT_3D project

Dust Observations in Earth's Atmosphere

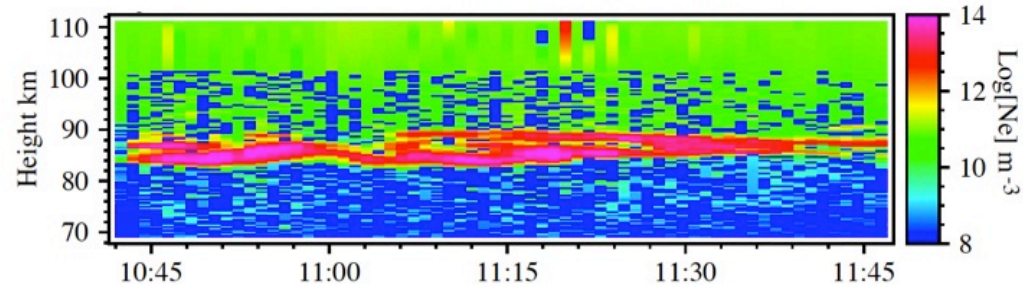
Noctilucent Clouds

Photo Peter Dalin, IRF Kiruna

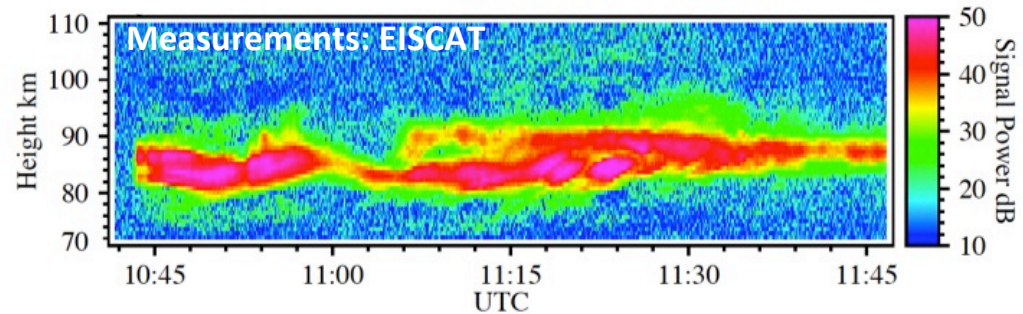


Polar Mesospheric Summer Echoes

Tromso VHF – 20110711



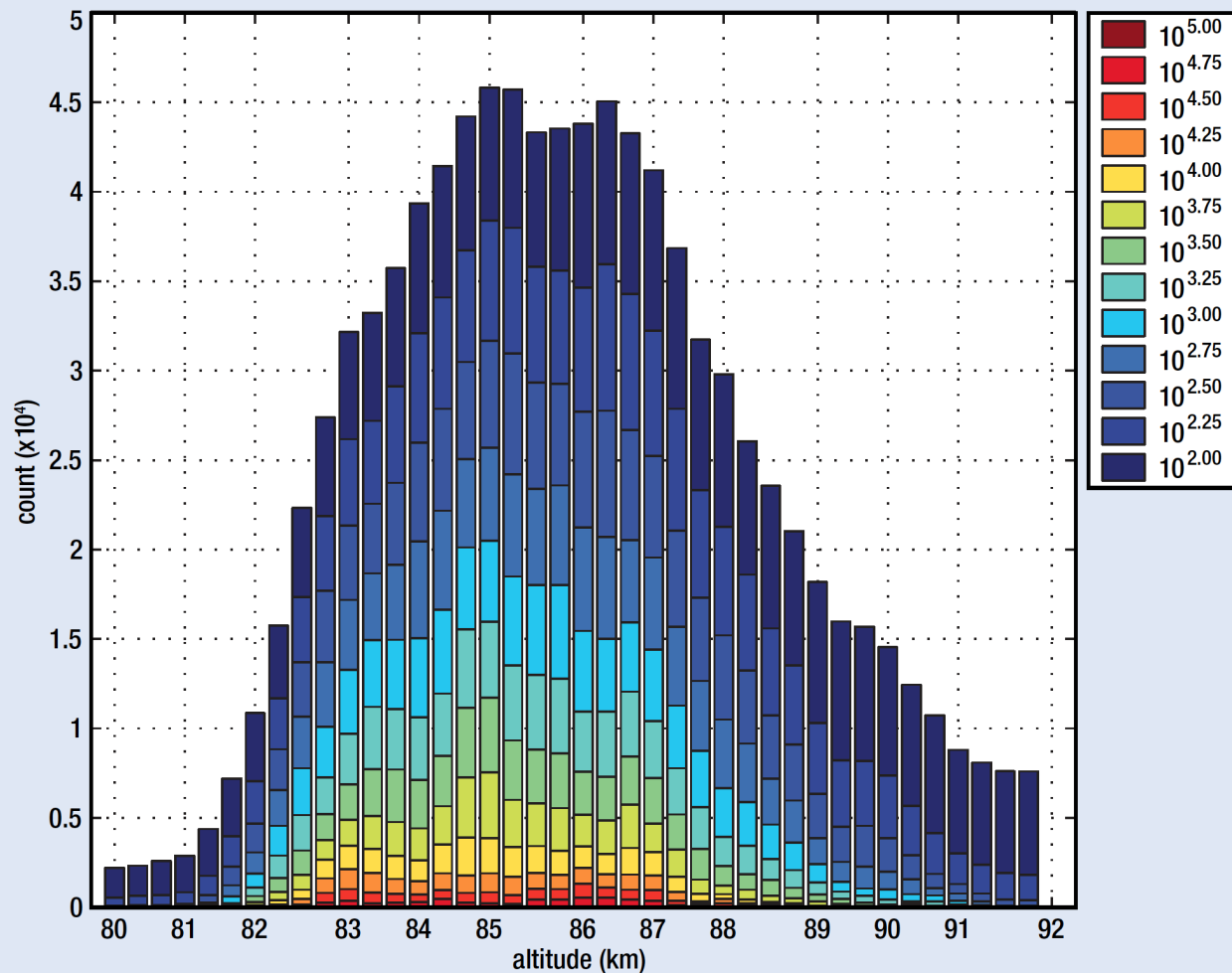
Kiruna VHF – 20110711



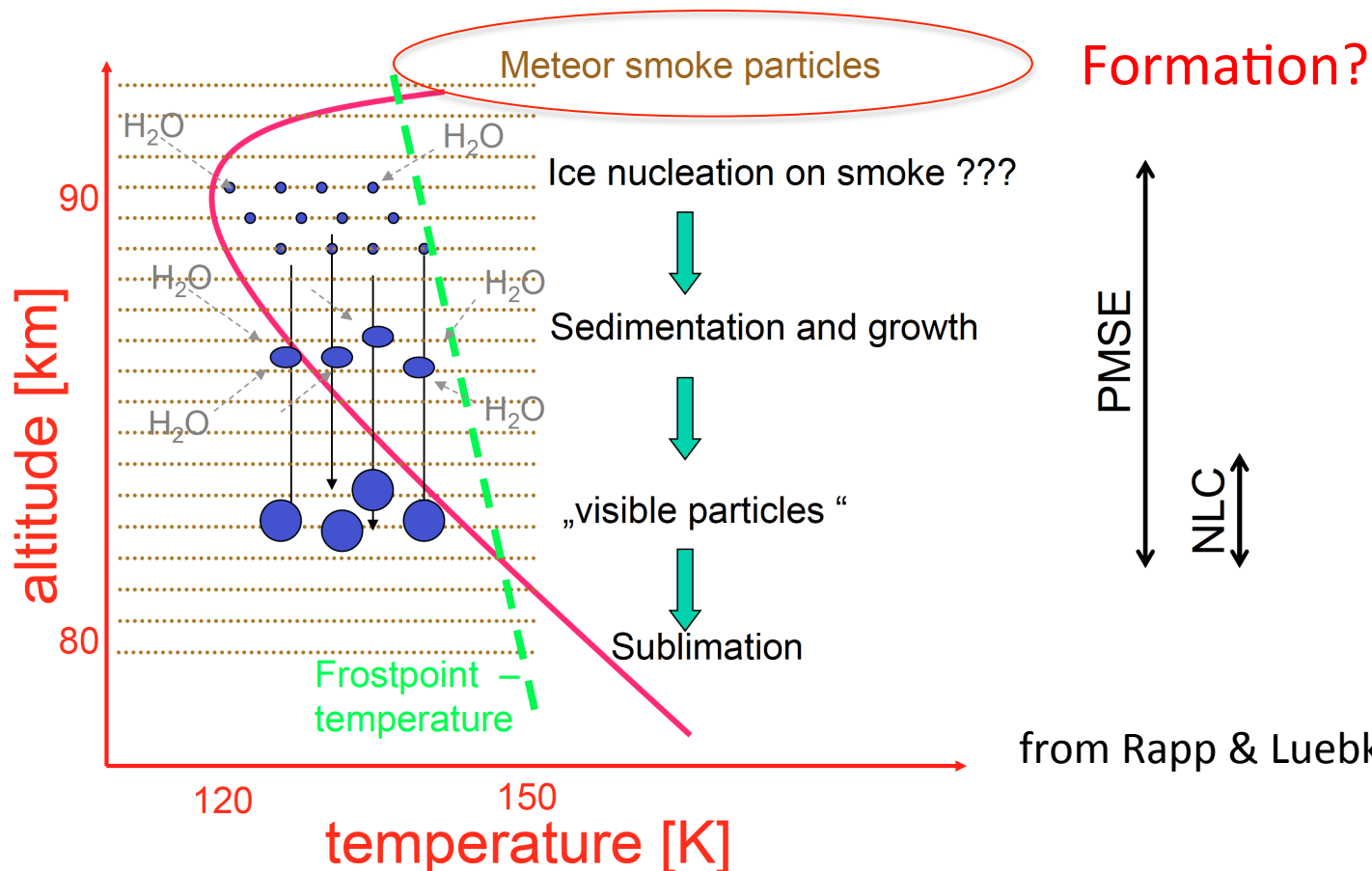
Dusty Plasma Studies: example PMSE

HARTQUIST *ET AL.*: POLAR MESOSPHERIC SUMMER ECHOES

2: PMSE occurrence rate as a function of height. PMSE relative strengths spanning a factor of 1000 have been assigned colours. Dark red indicates the strongest and dark blue the weakest PMSEs. The weak tail at 90km and above is not due to PMSE backscatter. Instead it is caused by incoherent scattering on free electrons produced sporadically in high abundance by energetic particle precipitation. (From Naesheim 2008)

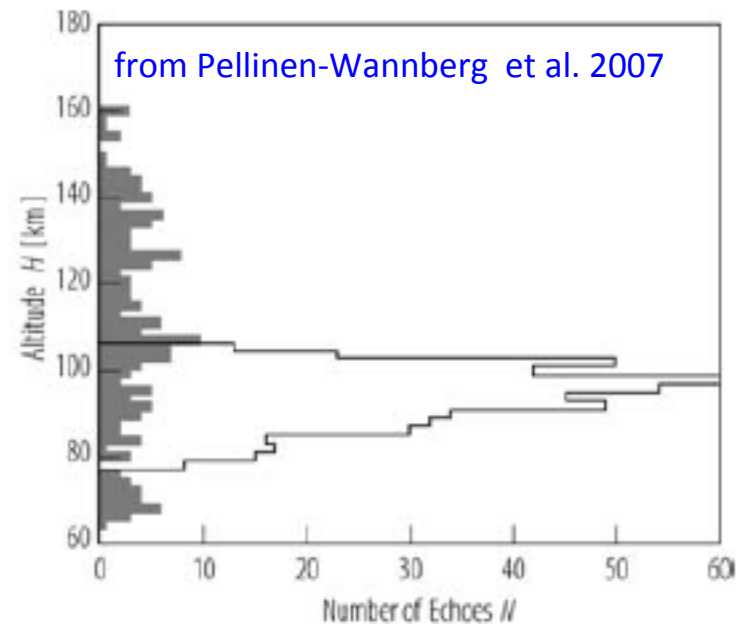
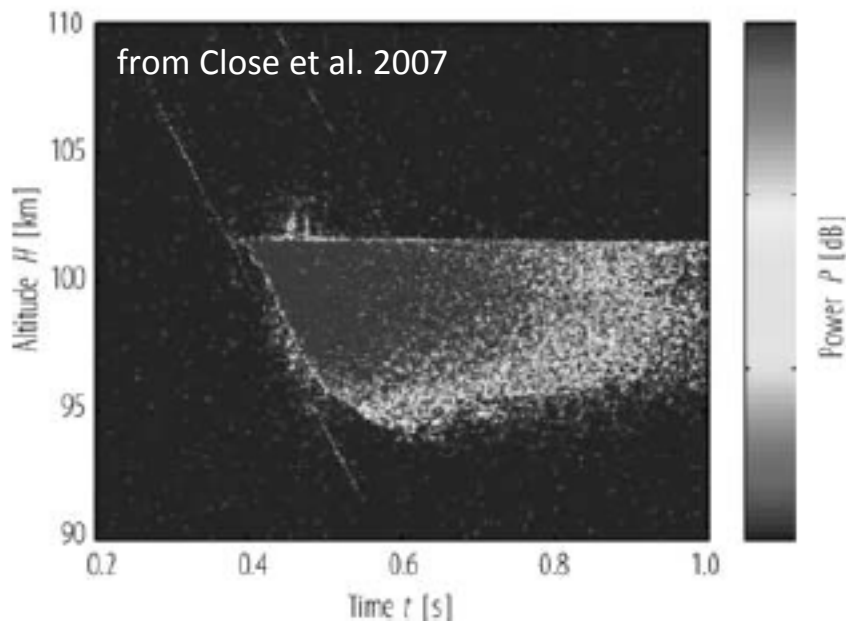


Formation Model



Solar System Studies: example meteor observations

(a) The intensity of a meteor radar signal as function of time and altitude measured with the ALTAIR VHF radar (160 MHz) [07Clo]. The diagonal line at the left is the head echo signal, while the signal on the right of this line that extends in altitude and time is the non-specular trail signal. (b) Altitude distributions of the meteor head echoes (open histogram) and trail echoes (filled histogram) recorded during the December 1990 and December 1991 observing periods with EISCAT [04Pel].

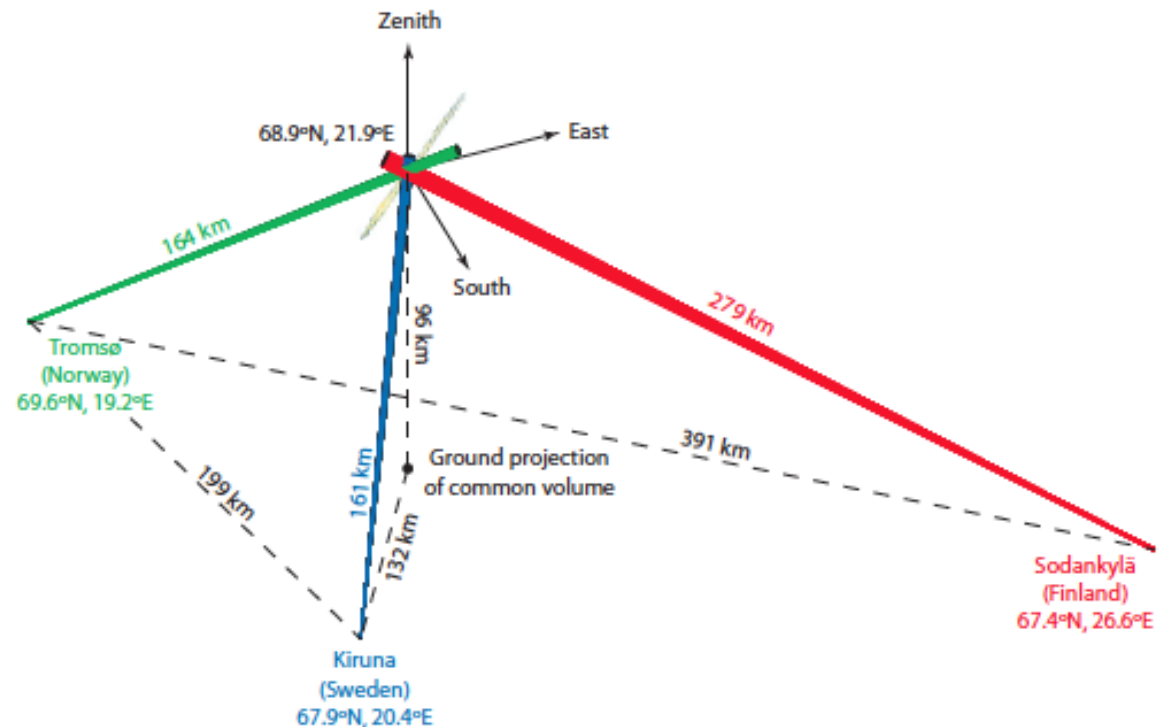


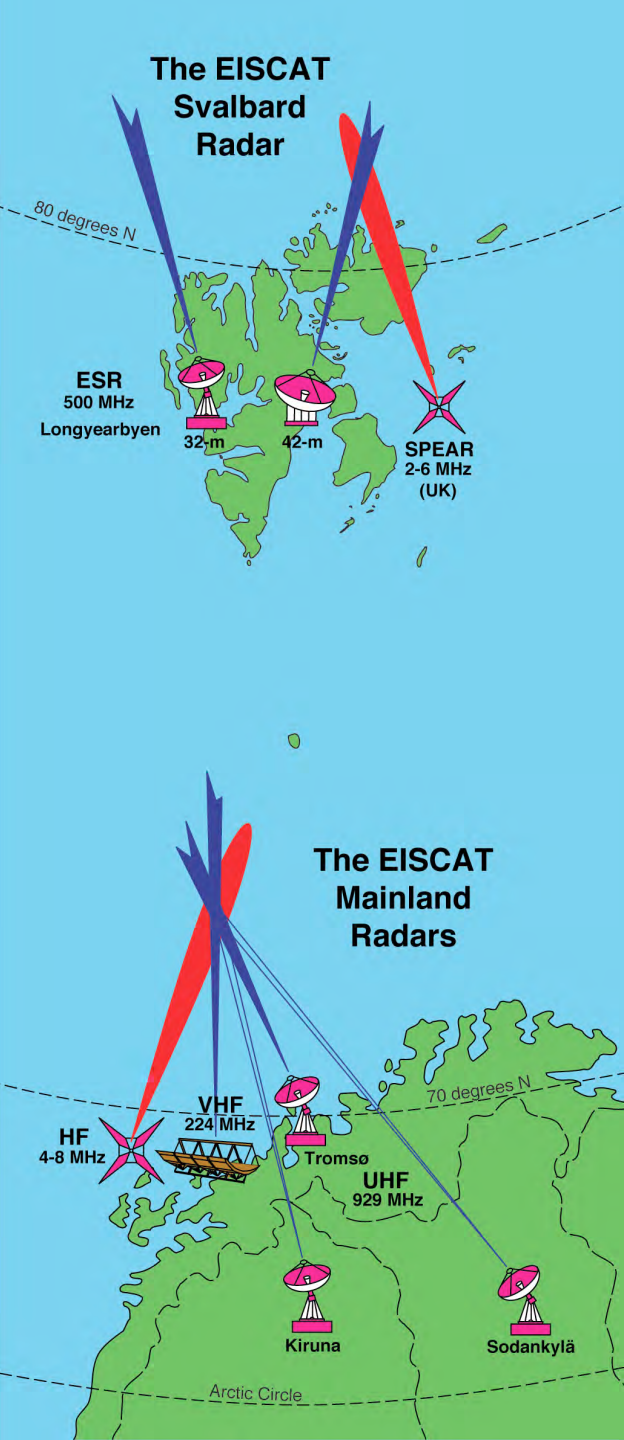
High-resolution meteor exploration with tristatic radar methods

Direct measurement of the meteor headcho
velocity vector provides orbital information

Johan Kero

IRF Scientific Report 293, 2008





EISCAT Incoherent Scatter Radars

EISCAT scientific association

Incoherent scatter measurements

Examples for other radar targets

EISCAT_3D project

February 2012 Project Plan

EISCAT_3D

Research infrastructure for incoherent scatter radar studies of the environment

Document prepared by EISCAT Scientific Association

27th February 2012



1 Executive Summary

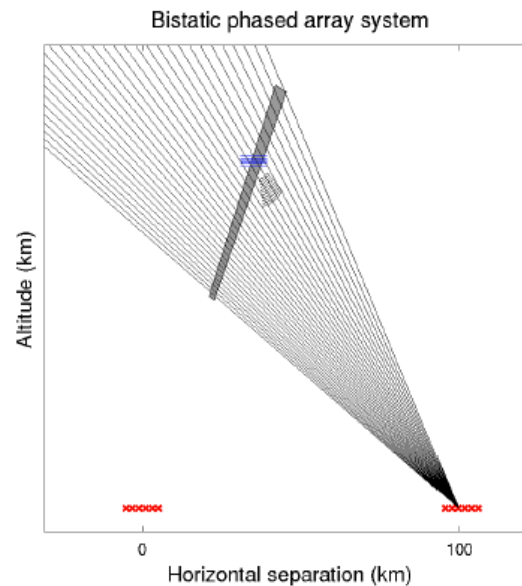
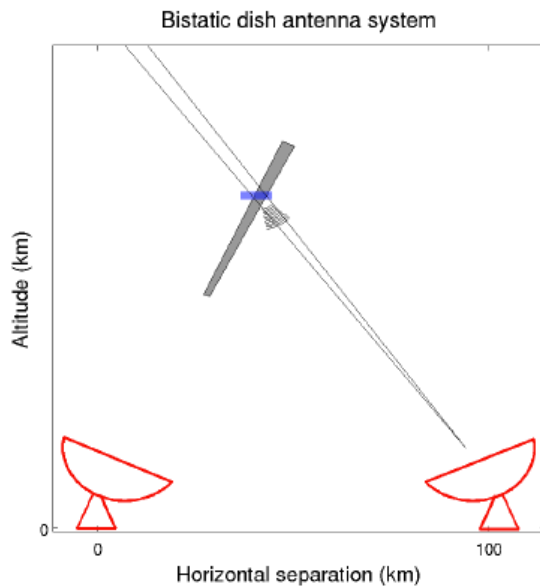
EISCAT_3D will be a world-leading international Research Infrastructure, using the incoherent scatter technique to study how the Earth's atmosphere is coupled to space. EISCAT_3D will provide an advanced plasma physics laboratory for studying microscale phenomena, a key atmospheric monitoring instrument for climate and space weather studies and an essential element in international global multi-instrument campaigns for studying the environment.

EISCAT_3D concept

+ multi-static phased array radars
+ advanced digital processing

=

**continuous observations & high flexibility
beam steering & volumetric imaging**





EISCAT_3D Baseline Design

System

5 sites (including one with Tx~10 MW and one with Tx~1 MW), multiple outlying sub-arrays at all sites, arbitrary Tx/Rx polarisation

Antenna Characteristics

| | |
|---|--|
| Type | Phased array |
| Average number of antenna elements per site | 10,000 |
| 3 dB receive bandwidth | 30 MHz |
| Gain | ~50 dBi |
| Beam-width | 0.8° |
| Transverse resolution at 100 km | < 50 m (depending on integration time) |
| Grating-lobe free radiation pattern | Down to elevations < 35° |

Transmitter Characteristics

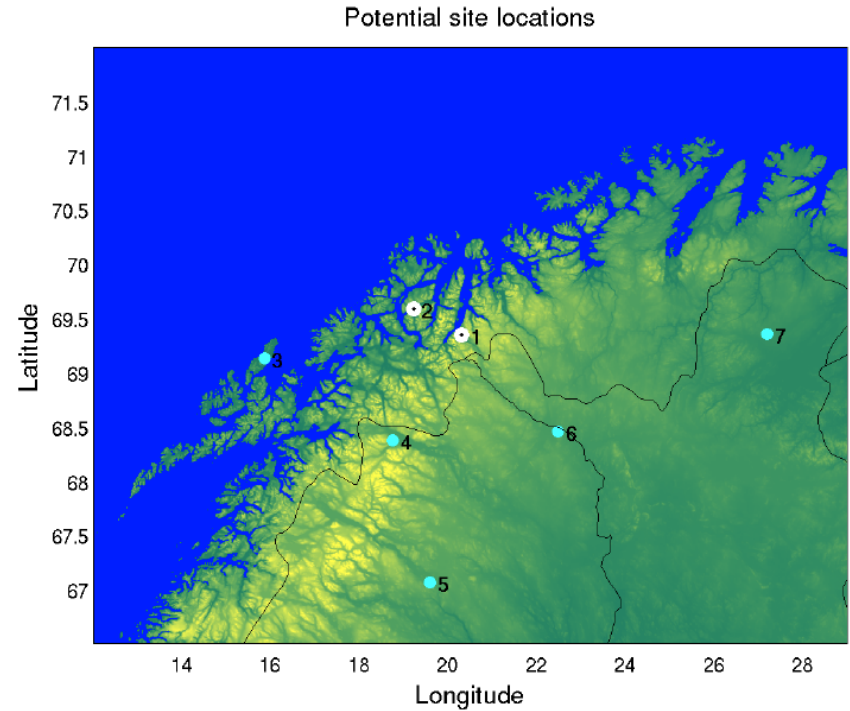
| | |
|----------------------------|---|
| Type | Pulsed |
| Duty cycle | ≥ 25 % |
| Centre frequency | 233 MHz |
| Modulation bandwidth | ~5 MHz |
| Pulse length | 0.25–3000 μs |
| Pulse repetition frequency | Arbitrary |
| Modulation | Arbitrary phase, polarisation and amplitude |



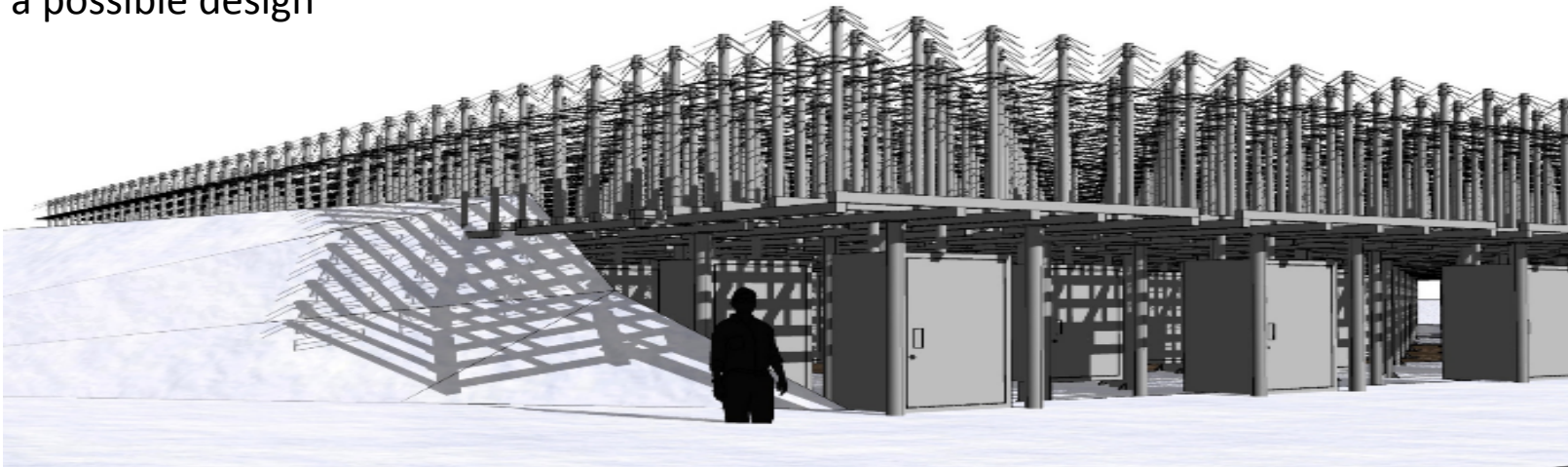
How will it look?

Baseline: core site & 4 remote sites

community agrees on list of 7 potential sites
will permit observations combined with rocket
flights from Andoya (N) and Esrange (S)



a possible design



Design Plan

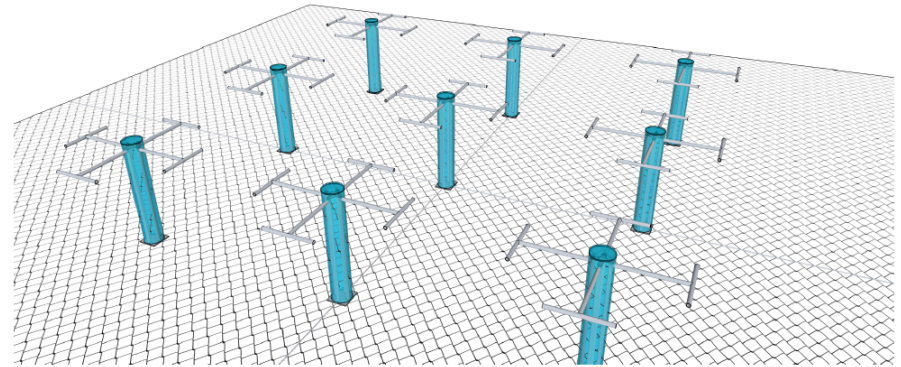


Figure 6: One possible design of the antenna elements. These elements are built with 2 crossed shortened dipoles with capacitive loads at the ends. This makes the antenna foot-prints smaller than half a wavelength. The antennas are mounted above a ground-plane mesh.

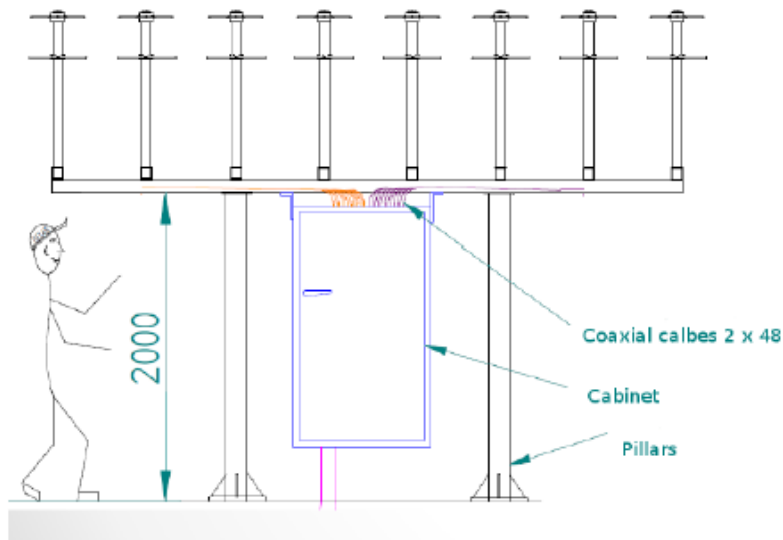


Figure 5: The antenna-group structure, that makes up the unit building block for the arrays. The antenna elements are protected from varying ground conditions at the elevated plane. The electronics contained in the cabinet provide power, timing, signal processing and network for data transfer.

Table 2: Comparison of measurement capabilities between the current EISCAT UHF radar system and the future EISCAT_3D.

| Measurement type | Current UHF $t(s)$ | Future EISCAT_3D $t(s)$ | | Improvement factor | |
|---|-----------------------|-------------------------------|---------|-----------------------|---------|
| | | 3 sites | 5 sites | 3 sites | 5 sites |
| Isotropic parameters at 110 km altitude | 4.0 | 0.024 | 0.018 | 160 | 200 |
| Isotropic parameters at 300 km altitude | 15.0 | 0.3 | 0.17 | 50 | 85 |
| Vector velocities at 110 km altitude | 300 | 6 | 1 | 50 | 300 |
| Vector velocities at 300 km altitude | 1700 | 95 | 20 | 18 | 80 |
| Monitoring data products as a function of altitude: electron density, electron and ion temperature, ion drift velocity: | | | | | |
| Other monitoring data products: Meteor influx and orbit parameters | | | | | |
| New Measurement capabilities: <ul style="list-style-type: none"> • Instantaneous, adaptive control of beam positions • Simultaneous multiple beams/interlaced beams with sub-pulses in different directions • High-resolution coding utilising phase, polarisation and amplitude • Aperture synthesis imaging – fine-scale 3-D imaging (sub-beam-width) • multi-beam volume imaging – large/small-scale 3D imaging (10 to 100s km horizontal coverage) • full-profile vector-wind measurements – large/small-scale 3D vector imaging • high-speed object tracking | | | | | |

EISCAT_3D bottom up:

Preparatory Phase Project

Funded from October 2010 – September 2014

by European Commission / FP7 INFRASTRUCTURES call:

“Construction of new infrastructures”

Aim: ensure that the EISCAT_3D project will reach a sufficient level of maturity with **respect to technical, legal and financial issues** so that the construction of the EISCAT_3D radar system can begin **immediately after the conclusion of the phase.**

Participants: University of Oulu, Luleå University of Technology, Swedish Institute of Space Physics, University of Tromsø, Science and Technology Facilities Council (UK), the Swedish Research Council, National Instruments, Uppsala University & EISCAT Scientific Association as the project coordinator.

EISCAT_3D Budget & Funding Applications

Investment: Baseline design 135 MEU

123 MEUR & 12 MEUR contingency

Annual budget \approx 8 MEUR (69MKSEK) in 2022

14 % site operation, 35 % radar operation, 50 % staff cost

users in host countries N,S,F plan proposals for:
to start implementation in 2014 (proposals \approx 80 MEU)

Time line:

Norway: funding proposal submitted October 2012

Sweden: funding proposal submitted March 2013

Finland: roadmap proposal to be submitted in 2013

Japan: roadmap proposal to be submitted in 2013

EISCAT_3D bottom up:



annual meeting of the preparatory phase project

annual EISCAT_3D user meeting

bi-annual EISCAT Scientific Symposium

bi-annual reports to Council and Oversight Committee

EISCAT_3D is Research Infrastructure for the Environment on ESFRI Roadmap

- offers the link to other environmental research
- helps extending user community
- helps attracting new member countries
- enhances chances for international collaboration for the association and for individual users

Development of Science case for the new system coordinated by Dr. Anita Aikio (Oulo Univ., Finland) and Dr. Ian McCrea (STFC, United Kingdom)



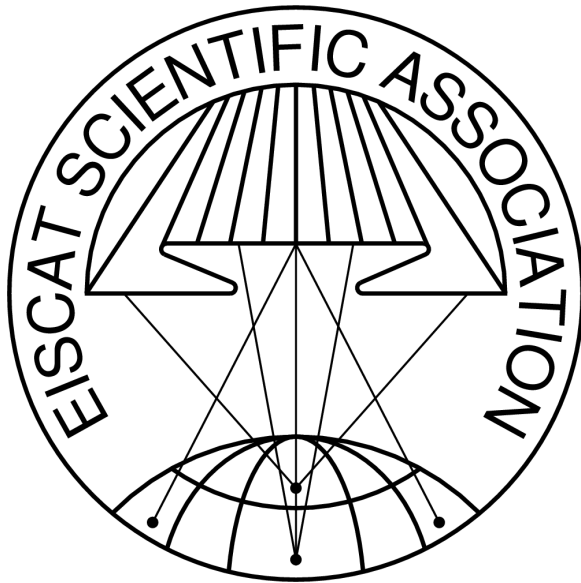
EISCAT_3D users:

- 1 experienced EISCAT users
- 2 new users attracted by the enhanced conventional capabilities and/or by the capabilities that are inherent to the new system
- 3 environmental and space weather modellers and service providers ('continuous data sets')
- 4 occasional users interested in EISCAT_3D for short-duration research projects or as source of supporting data (campaigns)



EISCAT aims to expand its user community & membership

please check <https://www.eiscat.se/eiscat2014>



<http://www.eiscat.se/>

May 2013

EISCAT Scientific Association is currently aiming to invest in a cutting-edge EISCAT_3D radar system, to expand its user community and to expand its membership. EISCAT¹ is revising its statutes with the aim to open up access to all scientists in the field and seeks new members who wish to contribute to the progress of the Association. The Association is revising its user access and membership policy, and potential new members or users are strongly encouraged to discuss their aspirations with the EISCAT Council members or EISCAT executives. There are several ways for scientists to access EISCAT instruments and data: Associate Membership, Affiliate Membership and individual user access based on scientific merit.

EISCAT Associates provide the basic conditions for running the Association, take full responsibility for the Association and determine the overall direction of its development. They are expected to make a significant initial payment into the Association that is related to achieving its scientific and strategic goals and to contribute to the operational costs, maintenance, and decommissioning in a proportion that is related to their initial payment and that allows that the minimum required operation costs be covered by the Associates. It is understood that Associates intend to make a long-term commitment and that they give a 5-year notice before leaving the association. At present the initial payment from a new Associate should ideally amount to 5 % of the total investment currently planned for the new EISCAT instruments². The Associates decide on a common observation program and on data formats, they have guaranteed observation time according to an agreed time-share formula and access to the archived data of the Association. Associates will normally be National Research Councils, their equivalents, or major national institutions.

EISCAT Affiliates can join the association on a smaller level of financial contribution responsibility, and other commitments. The Affiliates have guaranteed observation time according to an agreed time-share formula and access to the archived data of the association. The expected minimum payment of Affiliates to the association should grant observation time that permits the Affiliate to run at least one independent observation campaign per year³. Affiliates will normally be individual institutions or foundations.

The EISCAT Associates establish the governing EISCAT Council and its committees. Affiliates have vested membership in the EISCAT Science Advisory Committee and observer status in Council.

EISCAT encourages scientists to use its data and instrumentation for high-level research projects and grants observation time to external users through an open peer-review programme that is coordinated by a scientific committee established by the association. Associates and Affiliates are expected to distribute their observation time to individual users in a way that ensures that the EISCAT system is used for scientific work of the highest standard.

¹ EISCAT is currently funded and operated by research councils of Norway, Sweden, and Finland and by funding bodies in Japan, China and the United Kingdom (EISCAT Associates). France, Russia and Ukraine are affiliated partners. The host institutes of the present EISCAT systems are Sodankylä Geophysical Institute (independent department of University of Oulu), University of Tromsø and Swedish Institute of Space Physics. EISCAT Scientific Association is a Swedish non-profit organization.

² EISCAT at present plans a major investment into the new EISCAT_3D system that is equivalent to approximately 1 100 M\$ek (130 MEUR).

³ This corresponds at present to a minimum fee equivalent to 100 000 SEK (12 000 EURO).

